

ON A FAMILY OF RIEMANNIAN MANIFOLDS DEFINED ON AN m -DISK

Dedicated to Professor MASARU OSIMA on his 60th birthday

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1. The Riemannian manifold O_n^m

Let R^m be the m -dimensional coordinate space with the canonical coordinates u_1, u_2, \dots, u_m and D^m be the unit m -disk

$$(u, u) := \sum_i u_i u_i < 1,$$

where $u = (u_1, \dots, u_m)$. We denote the Riemannian manifold defined on D^m with the following metric :

$$(1.1) \quad ds^2 = (1 - \sum_i u_i u_i)^{n-2} \{ \sum_i du_i du_i - \sum_{i < j} (u_i du_j - u_j du_i)^2 \}$$

by O_n^m , where n is a real constant.

In order to give a meaning of (1.1), suppose that n is an integer ≥ 2 and consider the unit $(n+m-1)$ -sphere $S^{n+m-1} \subset R^{n+m}$ given by $\sum_{i=1}^{n+m} u_i u_i = 1$. Let us consider as

$$R^{n+m} = R^n \times R^m$$

and take a smooth curve C in D^m . Then, for C we construct an n -dimensional submanifold $M^n(C)$ in S^{n+m-1} as follows :

$$(1.2) \quad M^n(C) = \{ \cup S^{n-1}(\rho) \times u, u \in C \},$$

where

$$(1.3) \quad \rho = \rho(u) := \sqrt{1 - \sum_{i=1}^m u_i u_i}$$

and $S^{n-1}(\rho)$ is the $(n-1)$ -sphere of radius ρ about the origin of R^n .

The n -dimensional volume of $M^n(C)$ is clearly given by the formula :

$$(1.4) \quad V(M^n(C)) = c_{n-1} \int_C \rho^{n-1} \sqrt{d\rho d\rho + (du, du)},$$

where c_{n-1} is the volume of the unit $(n-1)$ -sphere S^{n-1} , i. e.

$$c_{n-1} = 2\pi^{n/2} / \Gamma(n/2).$$

Lemma 1. *The metric (1.1) can be written as*

$$dS^2 = \rho^{2(n-1)} \{d\rho d\rho + (du, du)\}.$$

Proof. From $\rho^2 = 1 - (u, u)$, we have $\rho d\rho = -(u, du)$. Hence

$$\begin{aligned} \rho^{2(n-1)} \{d\rho d\rho + (du, du)\} &= \rho^{2(n-1)} \left\{ \frac{(u, du)^2}{\rho^2} + (du, du) \right\} \\ &= \rho^{2(n-2)} \{(u, du)^2 + (1 - (u, u)) (du, du)\} \\ &= \rho^{2(n-2)} \{(du, du) - ((u, u) (du, du) - (u, du)^2)\} \\ &= (1 - \sum_i u_i u_i)^{n-2} \left\{ \sum_i du_i du_i - \sum_{i < j} (u_i du_j - u_j du_i)^2 \right\} \end{aligned}$$

Q. E. D.

Lemma 1 and (1.4) imply immediately the following

Lemma 2. *An extremal of the volume of the family of the submanifolds $\{M^n(C); C \text{ is a smooth curve in } D^m\}$ in the $(n+m-1)$ -sphere corresponds to a geodesic of O_n^m and vice versa.*

Remark. In the definition of O_n^m , we consider n as a real number. Especially, the cases of $n=1, 0$, have the following meanings:

O_1^m is the representation of the north hemisphere of S^m through the orthogonal projection onto the equatorial hyperplane of $R^{m+1} (\supset S^m)$.

O_0^m is the Cayley-Klein representation of the hyperbolic m -space of curvature 1. In fact, for any two points $u, v = u + du$ in D^m , let p, q be the points of intersection of the straight line joining u and v and the unit $(m-1)$ -sphere $S^{m-1} = \partial D^m$. Denoting p and q in the form $(1-\lambda)u + \lambda v$, we have easily

$$(du, du) \lambda^2 + 2(u, du) \lambda - \rho^2 = 0,$$

hence

$$\lambda = \frac{-(u, du) \pm \delta_s}{(du, du)} = \lambda_{\pm},$$

where

$$\delta_s^2 = (du, du) - \sum_{i < j} (u_i du_j - u_j du_i)^2.$$

Thus, we have the cross ratio of the four points u, v, p, q :

$$R(u, v : p, q) = \frac{\lambda_+}{1-\lambda_+} \cdot \frac{1-\lambda_-}{\lambda_-} = \frac{\rho^2 - (u, du) + \delta_s}{\rho^2 - (u, du) - \delta_s},$$

from which

$$\begin{aligned} \log R(u, v : p, q) &= \log\left(1 - \frac{(u, du) - \delta_s}{\rho^2}\right) - \log\left(1 - \frac{(u, du) + \delta_s}{\rho^2}\right) \\ &= \frac{2\delta_s}{\rho^2} + [2], \end{aligned}$$

where $[2]$ denotes the part of higher order of du , when we regard du as infinitesimal. Therefore, the Riemannian metric of the hyperbolic m -space H^m in this representation can be written as

$$ds^2 = \frac{a\delta_s^2}{\rho^4} = a(1 - (u, u))^{-2} \left\{ (du, du) - \sum_{i < j} (u_i du_j - u_j du_i)^2 \right\},$$

where a is a constant.

2. Geodesics of O_n^m

We shall investigate the geodesics of O_n^m .

From (1. 1), the components of the metric tensor of O_n^m are

$$(2. 1) \quad g_{ij} = \rho^{2n-4} (\rho^2 \delta_{ij} + u_i u_j)$$

and

$$(2. 2) \quad g^{ij} = \rho^{-2n+2} (\delta^{ij} - u^i u^j),$$

where δ_{ij} are the Kronecker's δ and $u^i = u_i$. From (2. 1), we have

$$\frac{\partial g_{ij}}{\partial u^k} = \rho^{2n-6} \{ \rho^2 (u_i \delta_{jk} + u_j \delta_{ik}) - 2(n-1) \rho^2 u_k \delta_{ij} - 2(n-2) u_i u_j u_k \}$$

and

$$\begin{aligned} (2. 3) \quad [ij, k] &:= \frac{1}{2} \left\{ \frac{\partial g_{jk}}{\partial u^i} + \frac{\partial g_{ik}}{\partial u^j} - \frac{\partial g_{ij}}{\partial u^k} \right\} \\ &= \rho^{2n-6} [\rho^2 \{ n u_k \delta_{ij} - (n-1) (u_i \delta_{jk} + u_j \delta_{ik}) \} \\ &\quad - (n-2) u_i u_j u_k]. \end{aligned}$$

Thus, using the Einstein convention, the Christoffel's symbols of O_n^m in the coordinates u^i are given by

$$\begin{aligned}
\left\{ \begin{matrix} l \\ ij \end{matrix} \right\} &= g^{lk} [ij, k] \\
&= \rho^{-4} (\delta^{lk} - u^l u^k) [\rho^2 \{ nu_k \delta_{ij} - (n-1)(u_i \delta_{jk} + u_j \delta_{ik}) \\
&\quad - (n-2) u_i u_j u_k \}] \\
&= \rho^{-4} [\rho^2 \{ nu^l \delta_{ij} - (n-1)(u_i \delta_j^l + u_j \delta_i^l) \} - (n-2) u_i u_j u^l \\
&\quad - \rho^2 u^l \{ n(u, u) \delta_{ij} - 2(n-1) u_i u_j \} + (n-2)(u, u) u^l u_i u_j],
\end{aligned}$$

i. e.

$$(2.4) \quad \left\{ \begin{matrix} l \\ ij \end{matrix} \right\} = \frac{1}{\rho^2} [n(\rho^2 \delta_{ij} + u_i u_j) u^l - (n-1)(u_i \delta_j^l + u_j \delta_i^l)].$$

Theorem 1. For any p -dimensional linear space E^p ($p < m$) through the origin of R^m , $D^m \cap E^p$ is a totally geodesic submanifold of O_n^m , which is an O_n^p .

Proof. As easily seen by Lemma 1, the metric (1.1) is invariant under the rotations of R^m about the origin. Hence, we may suppose that E^p is given by

$$u_{p+1} = u_{p+2} = \cdots = u_m = 0.$$

For any tangent vector fields $X = \sum_{a=1}^p X^a \partial / \partial u^a$, $Y = \sum_{a=1}^p Y^a \partial / \partial u^a$ of $E^p \cap D^m$, we put

$$\nabla_x Y = \sum_{i=1}^m Z^i \partial / \partial u^i,$$

where ∇ denotes the covariant differentiation of O_n^m and Z^i is given by

$$Z^i = \sum_a \frac{\partial Y^i}{\partial u^a} X^a + \sum_{a,b} \left\{ \begin{matrix} i \\ ab \end{matrix} \right\} Y^a X^b.$$

By means of (2.4), on $E^p \cap D^m$ we have

$$\begin{aligned}
\left\{ \begin{matrix} i \\ ab \end{matrix} \right\} &= -\frac{n-1}{\rho^2} (u_a \delta_b^i + u_b \delta_a^i) = 0 \\
&\text{for } i > p \text{ and } a, b \leq p.
\end{aligned}$$

Hence we have

$$Z^i = 0 \quad \text{for } i > p,$$

that is $\Delta_x Y$ is also a tangent vector field of $E^p \cap D^m$. This shows that

$E^n \cap D^n$ is a totally geodesic submanifold of O_n^n , which can be considered as an O_n^n by the induced metric from O_n^n . Q. E. D.

Corollary. *Any geodesic of O_n^n lies on a plane through the origin of R^n and can be considered as a geodesic of O_n^n .*

3. Certain properties of $M^n(C)$ in S^{n+m-1}

In this section, we suppose that n is an integer ≥ 2 . By means of Lemma 2, an extremal of the volume of the family of the submanifolds $\{M^n(C)\}$ corresponds to a geodesic of O_n^n and then C is also a geodesic of an $O_n^n \subset O_n^n$ by Corollary of Theorem 1. Accordingly, $M^n(C)$ can be considered as

$$M^n(C) \subset S^{n+1} \subset S^{n+m-1}$$

and it belongs to a family of hypersurfaces of S^{n+1} , which has two principal curvatures with multiplicity 1 and $n-1$.

Now, let C be a smooth curve in D^n not passing through the origin of D^n and \bar{s} be its arclength. We take an orthonormal frame field $(q, \bar{\xi}_1, \bar{\xi}_2, \dots, \bar{\xi}_m)$ along C in R^n such that

$$(3.1) \quad q = f \bar{\xi}_1 - h \bar{\xi}_2 \quad (h \geq 0),$$

where q also denotes the position vector of the moving point of C and

$$(3.2) \quad \bar{\xi}_1 = \frac{dq}{d\bar{s}}.$$

If q is not parallel to $\bar{\xi}_1$, $\bar{\xi}_2$ is determined uniquely at q . We have easily

$$(3.3) \quad 1 - \rho^2 = f^2 + h^2,$$

where $\rho^2 = 1 - (q, q)$ by (1.3). From (3.2) and (3.3) we obtain

$$\rho \frac{d\rho}{d\bar{s}} = - \left(q, \frac{dq}{d\bar{s}} \right) = - (q, \bar{\xi}_1) = -f,$$

hence

$$(3.4) \quad \frac{d\rho}{d\bar{s}} = - \frac{f}{\rho}.$$

We put

$$(3.5) \quad \bar{k}_a : = \left(\frac{d\bar{\xi}_2}{d\bar{s}}, \bar{\xi}_a \right), \quad a = 1, 3, \dots, m.$$

Especially we have

$$(3.6) \quad \bar{k}_1 = \left(\frac{d\bar{\xi}_2}{d\bar{s}}, \bar{\xi}_1 \right) = - \left(\frac{d\bar{\xi}_1}{d\bar{s}}, \bar{\xi}_2 \right),$$

which shows that $-\bar{k}_1 \bar{\xi}_2$ is the orthogonal projection of the principal curvature vector $\frac{d\bar{\xi}_1}{d\bar{s}}$ of C onto the plane through the origin of D^m and the tangent line of C at q .

On the other hand, let $(\bar{e}_1, \dots, \bar{e}_n)$ be the moving orthonormal frame of R^n at the origin and put

$$(3.7) \quad d\bar{e}_i = \sum_j \omega_{ij} \bar{e}_j, \quad \bar{\omega}_{ij} + \bar{\omega}_{ji} = 0.$$

The generating moving point p of $M^n(C)$ is given by

$$(3.8) \quad p = q + \rho \bar{e}_n = \rho \bar{e}_n + f \bar{\xi}_1 - h \bar{\xi}_2,$$

from which we obtain by differentiation

$$dp = \rho \sum_{a=1}^{n-1} \omega_{na} \bar{e}_a + d\bar{s} \left(\frac{d\rho}{d\bar{s}} \bar{e}_n + \bar{\xi}_1 \right).$$

Using (3.3) and (3.4), if we put

$$(3.9) \quad e_n = \bar{e}_n, \quad e_n = \frac{-f \bar{e}_n + \rho \bar{\xi}_1}{\sqrt{1-h^2}},$$

$$\omega_a = \rho \bar{\omega}_{na}, \quad \omega_n = \frac{\sqrt{1-h^2}}{\rho} d\bar{s},$$

then we have the equality

$$dp = \sum_{i=1}^n \omega_i e_i$$

and (p, e_1, \dots, e_n) is an orthonormal frame of $M^n(C)$ at p .

Next, if we put

$$(3.10) \quad e_{n+1} = -\frac{h}{\sqrt{1-h^2}} (\rho \bar{e}_n + f \bar{\xi}_1) - \sqrt{1-h^2} \bar{\xi}_2,$$

then

$$\|e_{n+1}\|^2 = \frac{h^2}{1-h^2}(\rho^2 + f^2) + 1 - h^2 = 1.$$

e_{n+1} is clearly orthogonal to e_1, e_2, \dots, e_n . Using (3.3) and (3.8), we obtain

$$\begin{aligned} (\mathfrak{p}, e_{n+1}) &= (\rho \bar{e}_n + f \bar{\xi}_1 - h \bar{\xi}_2, e_{n+1}) \\ &= -\frac{h\rho^2}{\sqrt{1-h^2}} - \frac{hf^2}{\sqrt{1-h^2}} + h\sqrt{1-h^2} = 0, \end{aligned}$$

which shows that e_{n+1} is also tangent to S^{n+m-1} .

Furthermore, putting

$$(3.11) \quad e_\lambda = \bar{\xi}_{\lambda-n+1}, \quad \lambda > n+1,$$

we obtain a moving orthonormal frame $(\mathfrak{p}, e_1, \dots, e_{n+m-1})$ of S_{n+m-1} defined along $M'(C)$. From this frame, we obtain by the covariant differentiation D on S^{n+m-1} the following:

$$\begin{aligned} \omega_{a,n+1} &= (De_a, e_{n+1}) = (d\bar{e}_a, e_{n+1}) \\ &= (d\bar{e}_a, -\frac{h}{\sqrt{1-h^2}}(\rho \bar{e}_n + f \bar{\xi}_1) - \sqrt{1-h^2} \bar{\xi}_2) \\ &= \frac{h\rho \bar{\omega}_{na}}{\sqrt{1-h^2}} = \frac{h}{\sqrt{1-h^2}} \omega_a \quad \text{for } a = 1, 2, \dots, n-1 \end{aligned}$$

and

$$\begin{aligned} \omega_{n,n+1} &= (De_n, e_{n+1}) = (de_n, e_{n+1}) \\ &= \left(d \frac{-f \bar{e}_n + \rho \bar{\xi}_1}{\sqrt{1-h^2}}, e_{n+1} \right) = \frac{1}{\sqrt{1-h^2}} (d(-f \bar{e}_n + \rho \bar{\xi}_1), e_{n+1}). \end{aligned}$$

Since

$$\begin{aligned} -\sqrt{1-h^2} \omega_{n,n+1} &= \left(\left(-\frac{df}{d\bar{s}} \bar{e}_n + \frac{d\rho}{d\bar{s}} \bar{\xi}_1 + \rho \frac{d\bar{\xi}_1}{d\bar{s}} \right) d\bar{s} - f d\bar{e}_n, \right. \\ &\quad \left. \frac{h}{\sqrt{1-h^2}} (\rho \bar{e}_n + f \bar{\xi}_1) + \sqrt{1-h^2} \bar{\xi}_2 \right) \\ &= \left\{ \frac{h}{\sqrt{1-h^2}} \left(-\rho \frac{df}{d\bar{s}} + f \frac{d\rho}{d\bar{s}} \right) - \rho \sqrt{1-h^2} \bar{k} \right\} d\bar{s}, \end{aligned}$$

using (3.4) and (3.9) we have

$$\omega_{n,n+1} = \left\{ \frac{h}{\sqrt{(1-h^2)^3}} \left(f^2 + \rho^2 \frac{df}{ds} \right) + \frac{\bar{k}_1 \rho^2}{\sqrt{1-h^2}} \right\} \omega_n.$$

On the other hand, from (3. 1), (3. 2) and (3. 6) we obtain

$$\bar{\xi}_1 = \frac{dq}{ds} = \frac{df}{ds} \bar{\xi}_1 + f \frac{d\bar{\xi}_1}{ds} - \frac{dh}{ds} \bar{\xi}_2 - h \frac{d\bar{\xi}_2}{ds},$$

which implies

$$1 = \frac{df}{ds} - h \left(\bar{\xi}_1, \frac{d\bar{\xi}_2}{ds} \right) = \frac{df}{ds} - h \bar{k}_1,$$

i. e.

$$(3. 12) \quad \frac{df}{ds} = 1 + h \bar{k}_1.$$

Taking the inner product of the above equality with $\bar{\xi}_2$, we obtain easily

$$0 = f \left(\bar{\xi}_2, \frac{d\bar{\xi}_1}{ds} \right) - \frac{dh}{ds} = -\bar{k}_1 f - \frac{dh}{ds},$$

i. e.

$$(3. 13) \quad \frac{dh}{ds} = -\bar{k}_1 f.$$

We obtain analogously the following :

$$(3. 14) \quad f \left(\frac{d\bar{\xi}_1}{ds}, \bar{\xi}_a \right) = h \bar{k}_a, \quad a = 3, 4, \dots, n-1.$$

Using (3. 12) and (3. 3), we have

$$\frac{h}{\sqrt{(1-h^2)^3}} \left(f^2 + \rho^2 \frac{df}{ds} \right) + \frac{\bar{k}_1 \rho^2}{\sqrt{1-h^2}} = \frac{h}{\sqrt{1-h^2}} + \frac{\bar{k}_1 \rho^2}{\sqrt{(1-h^2)^3}}.$$

Hence, we obtain the following :

$$(3. 15) \quad \begin{cases} \omega_{a,n+1} = \frac{h}{\sqrt{1-h^2}} \omega_a, & a = 1, 2, \dots, n-1; \\ \omega_{n,n+1} = \left(\frac{h}{\sqrt{1-h^2}} + \frac{\bar{k}_1 \rho^2}{\sqrt{(1-h^2)^3}} \right) \omega_n. \end{cases}$$

Then, for $\lambda > n + 1$, by (3. 14) and (3. 9) we have

$$\begin{aligned}
 \omega_{a\lambda} &= (De_a, e_\lambda) = (d\bar{e}_a, \bar{\xi}_{\lambda-n+1}) = 0 \text{ for } 1 \leq a \leq n-1, \\
 \omega_{n\lambda} &= (De_n, e_\lambda) = (de_n, \bar{\xi}_{\lambda-n+1}) \\
 &= \frac{1}{\sqrt{1-h^2}} (d(-f\bar{e}_n + \rho\bar{\xi}_1), \bar{\xi}_{\lambda-n+1}) \\
 &= \frac{\rho}{\sqrt{1-h^2}} \left(\frac{d\bar{\xi}_1}{ds}, \bar{\xi}_{\lambda-n+1} \right) d\bar{s} = \frac{\rho}{\sqrt{1-h^2}} \cdot \frac{h}{f} \bar{k}_{\lambda-n+1} \cdot \frac{\rho}{\sqrt{1-h^2}} \omega_n \\
 &= \frac{h\rho^2}{f(1-h^2)} \bar{k}_{\lambda-n+1} \omega_n,
 \end{aligned}$$

i. e.

$$(3.16) \quad \begin{cases} \omega_{a\lambda} = 0, & a = 1, 2, \dots, n-1; \\ \omega_{n\lambda} = \frac{h\rho^2}{f(1-h^2)} \bar{k}_{\lambda-n+1} \omega_n. \end{cases}$$

Now we state the definition of principal normal vectors for a submanifold introduced by the author in [5]. In general, let M be a submanifold of a Riemannian manifold \bar{M} . A normal vector v at a point $x \in M$ is called a *principal normal vector* of M at x , if it satisfies the following condition :

There exists a tangent vector $u \in M_x$, $u \neq 0$, such that

$$T_u z = (u, z) v \quad \text{for all } z \in M_x,$$

where M_x denotes the tangent space of M at x and T is the shape operator of M in \bar{M} . u is called a *principal tangent vector* for v .

It is evident that all the principal tangent vectors for v and the zero vector span a linear tangent subspace, which we denote by $E(x, v)$.

A C^∞ normal vector field V of M is called a *regular principal normal vector field*, if V is a principal normal vector at each point x of M and $\dim E(x, V(x))$ is constant. When \bar{M} is of constant curvature, $E(M, V) = \cup_x E(x, V(x))$ is a complete distribution of M (Theorem 1, [5]).

Now, going back to the previous situation, by means of (3.15) and (3.16), the shape operator of $M^n(C)$ as a submanifold of S^{n+m-1} can be written as follows : For any tangent vectors $X = \sum_i X_i e_i$, $Z = \sum_i Z_i e_i$,

$$\begin{aligned}
 (3.17) \quad T_x Z &= \left\{ \frac{h}{\sqrt{1-h^2}} \sum_{a=1}^{n-1} X_a Z_a + \left(\frac{h}{\sqrt{1-h^2}} + \frac{\bar{k}_1 \rho^2}{\sqrt{(1-h^2)^3}} \right) X_n Z_n \right\} e_{n+1} \\
 &+ \frac{h\rho^2 X_n Z_n}{f(1-h^2)} \sum_{\lambda > n+1} \bar{k}_{\lambda-n+1} e_\lambda.
 \end{aligned}$$

The formula (3. 17) implies immediately the following

Theorem 2. $M = M^n(C)$ has two regular principal normal vector fields V and W given by

$$V = \frac{h}{\sqrt{1-h^2}} e_{n+1},$$

$$W = \left(\frac{h}{\sqrt{1-h^2}} + \frac{k_1 \rho^2}{\sqrt{(1-h^2)^3}} \right) e_{n+1} + \frac{h \rho^2}{f(1-h^2)} \sum_{\lambda > n+1} \bar{k}_{\lambda-n+1} e_\lambda,$$

if the tangent lines of C do not pass through the origin of D^n . Then $E(M, V)$ and $E(M, W)$ are distributions of dimension $n-1$ and 1, respectively and

$$E(M, V) \oplus E(M, W) = T(M).$$

On the distributions in a sphere as V and W , we have the following theorem (Theorem 6, [6]):

Theorem 3. Let $M^n (n \geq 3)$ be a minimal submanifold of $S^{n+p} \subset R^{n+p+1}$ with two regular principal normal vector fields V and W such that

$$E(M^n, V) \oplus E(M^n, W) = T(M^n).$$

Then, there exists an $(n+2)$ -dimensional subspace E^{n+2} of R^{n+p+1} through the origin such that

$$M^n \subset E^{n+2} \cap S^{n+p}.$$

Theorem 4. $M^n(C)$ is minimal in S^{n+m-1} if and only if C is a geodesic of O_n^m .

Proof. By Theorem 2, $M^n(C)$ has two regular principal normal vector fields V and W satisfying the condition as in Theorem 3.

If $M^n(C)$ is minimal in S^{n+m-1} , by Theorem 3 there exists an $(n+2)$ -dimensional linear subspace E^{n+2} of R^{n+m} through the origin such that

$$M^n(C) \subset E^{n+2} \cap S^{n+m-1}.$$

Hence, by the way of construction of $M^n(C)$, C must lie in a plane through the origin. Accordingly, by (3. 1), (3. 2) and (3. 5) we have

$$(3. 18) \quad \bar{k}_3 = \bar{k}_4 = \dots = \bar{k}_m = 0.$$

Thus, the condition that $M^n(C)$ is minimal becomes

$$(3.19) \quad \frac{nh}{\sqrt{1-h^2}} + \frac{\rho^2 \bar{k}_1}{\sqrt{(1-h^2)^3}} = 0$$

by means of (3.17). Hence, by a result in [4], C is a geodesic of O_n^2 . By means of Corollary of Theorem 1, C is also a geodesic of O_n^m .

Conversely, if C is a geodesic of O_n^m , then it lies in a plane through the origin. Thus, (3.18) is true for C . By means of (3.17), $M^n(C)$ is minimal if (3.19) is true. Using the direction angle t of C in the plane, we have

$$\bar{k}_1 = -1 / \left(h + \frac{d^2h}{dt^2} \right) \quad \text{and} \quad f = \frac{dh}{dt}.$$

Therefore, (3.19) can be written as

$$(3.20) \quad nh(1-h^2) \frac{d^2h}{dt^2} + \left(\frac{dh}{dt} \right)^2 + (1-h^2)(nh^2-1) = 0.$$

This is also a condition that C is a geodesic of O_n^2 (Proposition 1, [8]). Hence $M^n(C)$ must be minimal in S^{n+m-1} . Q. E. D.

Remark. In order to prove Theorem 4, we can use Lemma 2. But, we have to take care of the following fact. If $M^n(C_0)$ is minimal, we may consider C_0 is a smooth arc in D^m and it is extremal with respect to the n -dimensional volume of the family of $M^n(C)$ such that C are smooth curves in D^m with the same end points of C_0 .

Finally, we shall give a remark on the representation of O_n^m like the Poincaré one of $H^2 = O_0^2$.

Let us suppose that n is any real number and denote the line element (1.2) of O_n^m by

$$(3.21) \quad ds_n^2 = (1 - (u, u))^{n-2} [(1 - (u, u))(du, du) + (u, du)^2].$$

In D^m we take the change of coordinate system: $u = (u_1, \dots, u_m) \rightarrow x = (x_1, \dots, x_m)$ given by

$$(3.22) \quad u = \frac{2x}{1+r^2}, \quad r = \sqrt{(x, x)}.$$

Then, we have

$$1 - (u, u) = \left(\frac{1-r^2}{1+r^2} \right)^2$$

$$(du, du) = \frac{4}{(1+r^2)^4} \{(1+r^2)^2(dx, dx) - 4(x, dx)^2\},$$

$$(u, du) = \frac{4(1-r^2)}{(1+r^2)^3} (x, dx).$$

Substituting these into (3.21), we obtain

$$ds_n^2 = \frac{4(1-r^2)^{2(n-1)}}{(1+r^2)^{2n}} (dx, dx),$$

i. e.

$$(3.23) \quad ds_n^2 = \frac{4(1 - \sum_i x_i x_i)^{2(n-1)}}{(1 + \sum_i x_i x_i)^{2n}} \sum_j dx_j dx_j.$$

Especially, we have

$$(3.24) \quad ds_0^2 = \frac{4}{(1 - \sum_i x_i x_i)^2} \sum_i dx_i dx_i,$$

which is the Poincaré representation of the hyperbolic plane of curvature -1 . Hence, we have from (3.23) and (3.24)

$$ds_n^2 = \left(\frac{1 - \sum_i x_i x_i}{1 + \sum_i x_i x_i} \right)^{2n} ds_0^2.$$

Therefore, we may call the expression (3.24) the Poincaré representation of O_n'' .

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