# ON THE SCALAR CURVATURE OF IMMERSED MANIFOLDS

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In §1, we introduce the notion of  $\alpha$ -th scalar curvatures:  $\lambda_1, \dots, \lambda_N$ , and find the relationship between the scalar curvature and the  $\alpha$ -th scalar curvatures for an n-dimensional riemannian manifold isometrically immersed in a euclidean space  $E^{n+N}$  of dimension n+N. In §2, we use these new curvatures to find a characterization of hypersphere in higher dimensional euclidean space and find some inequalities. In the last section, we find an equality for submanifolds with vanishing scalar curvature which generalizes a result of  $\overline{O}$ tsuki.

### 1. i-th total absolute curvatures and $\alpha$ -th scalar curvatures

Let  $M^n$  be an n-dimensional closed riemmannian manifold i with an isometric immersion  $x: M^n \to E^{n+N}$ . Let  $F(M^n)$  and  $F(E^{n+N})$  be the bundles of orthonormal frames of  $M^n$  and  $E^{n+N}$ , respectively. Let B be the set of elements  $b=(p,e_1,\cdots,e_n,e_{n+1},\cdots,e_{n+N})$  such that  $(p,e_1,\cdots,e_n)\in F(M^n)$  and  $(x(p),e_1,\cdots,e_{n+N})\in F(E^{n+N})$  whose orientation is coherent with the one of  $E^{n+N}$ , identifying  $e_i$  with  $dx(e_i)$ ,  $i=1,2,\cdots,n$ . Then  $B\to M^n$  may be considered as a principal bundle with fibre  $O(n)\times SO(N)$ , and  $\bar{x}:B\to F(E^{n+N})$  is naturally defined by  $\bar{x}(b)=(x(p),e_1,\cdots,e_{n+N})$ . Let  $B_v$  be the set of unit normal vectors of  $M^n$  in  $E^{n+N}$ .

The structure equations of  $E^{n+N}$  are given by

(1) 
$$\begin{cases} dx = \sum_{A} \omega^{I}{}_{A}e_{A}, & de_{A} = \sum_{B} \omega^{I}{}_{AB}e_{B}, \\ d\omega^{I}{}_{A} = \sum_{B} \omega^{I}{}_{B} \wedge \omega^{I}{}_{BA}, & d\omega^{I}{}_{AB} = \sum_{C} \omega^{I}{}_{AC} \wedge \omega^{I}{}_{CB}, & \omega^{I}{}_{AB} + \omega^{I}{}_{BA} = 0 \\ A, B, C, \dots = 1, 2, \dots, n + N, \end{cases}$$

where  $\omega'_A$ ,  $\omega'_{AB}$  are differential 1-forms on  $F(E^{n+N})$ . Let  $\omega_A$ ,  $\omega_{AB}$  be the induced 1-forms on B from  $\omega'_A$ ,  $\omega'_{AB}$  by the mapping  $\tilde{x}$ .

Then we have

<sup>1)</sup> Manifolds, mappings, metrics, ... etc. are assumed to be differentiable and of class  $C^{\infty}$ . We restrict ourselves only to connected manifolds of dimenson  $n \ge 2$ .

(2) 
$$\omega_{\gamma} = 0, \quad \omega_{\gamma i} = \sum_{j} A_{\gamma i j} \omega_{j}, \quad A_{\gamma i j} = A_{\gamma j i}$$
$$i, j, \dots = 1, 2, \dots, n; \quad \tilde{r}, t, \dots = n+1, \dots, n \div N.$$

From (1) we get

(3) 
$$\begin{cases} d\omega_{i} = \sum_{j} \omega_{j} \wedge \omega_{ji}, \\ d\omega_{ij} = \sum_{k} \omega_{ik} \wedge \omega_{kj} + \frac{1}{2} \sum_{k,h} R_{ijkh} \omega_{k} \wedge \omega_{h}, \\ R_{ijkh} = \sum_{\gamma} A_{\gamma ih} A_{\gamma jk} - \sum_{\gamma} A_{\gamma ik} A_{\gamma jk}. \end{cases}$$

The volume element of M'' can be written as

(4) 
$$dV = \omega_1 \wedge \cdots \wedge \omega_n$$

The (N-1)-form

(5) 
$$d\sigma_{N-1} = \omega_{n+N,n+1} \wedge \cdots \wedge \omega_{n+N,n+N-1}$$

can be regarded as an (N-1)-form on  $B_v$ . The (n+N-1)-form  $dV \wedge d\sigma_{N-1}$  can be regarded as the volume element of  $B_v$ .

Let  $A_{\gamma ij}$ ;  $\gamma = n+1, \dots, n+N, i, j=1, 2, \dots, n$ , be given as in (2). The symmetric matrix  $(A_{\gamma ij})$ ,  $\gamma = n+1, \dots, n+N$ , is called the second fundamental form at  $(p, e_{\gamma})$ . we define the h-th mean curvature  $K_h(p, e_{\gamma})$  at  $(p, e_{\gamma}) \in B_v$  by

(6) 
$$\det \left( \delta_{ij} + t A_{\gamma ij} \right) = 1 + \sum_{k} \binom{n}{k} K_k(p, e_{\gamma}) t^k,$$

where  $\delta_{ij}$  is the Kronecker delta, t a parameter and  $\binom{n}{h} = n!/h!(n-h)!$ .

We call the integral

(7) 
$$K_i^*(p) = \int |K_i(p,e)|^{\frac{n}{i}} d\sigma_{N-1}$$

over the sphere of unit normal vectors at x(p), the *i*-th total absolute curvature of the immersion x at p, and we define as the *i*-th total absolute curvature of  $M^n$  itself the integral  $\int_{\mathbb{R}^n} K_i^*(p) dV$ .

In the following, the *geodesic codimension* of  $M^n$  in  $E^{n+N}$  means the minimum of codimensions of  $M^n$  in linear subspaces of  $E^{n+N}$  containing  $M^n$ .

In [3, 4], the author proved that

**Theorem A.** Let  $x: M^n \to E^{n+N}$  be an immersion of an n-dimensional closed manifold  $M^n$  into  $E^{n+N}$ . Then we have

(8) 
$$\int_{M^n} K_i^*(p) \ dV \ge 2c_{n+N-1}, \quad i=1, 2, \dots, n,$$

where  $c_{n+N-1}$  is the area of unit (n+N-1)-sphere. The equality of (8) holds when and only when  $M^n$  is imbedded as a hypersphere if i < n and as a convex hypersurface if i = n in an (n+1)-dimensional linear subspace of  $E^{n+N}$ .

**Remark 1.1.** If i=n, then Theorem A is the well-known Chern-Lashof's theorem [5]. In this case; the inequality (8) can be improved as

(9) 
$$\int_{M^n} K_i^*(p) dV \ge \sum_{i=0}^n \beta_i(M^n) c_{n+N-1},$$

where  $\beta_i$  ( $M^n$ ) is the *i*-th betti number of  $M^n$ .

To describe how  $K_2(p,e)$  depends on e, we take a local cross-section of  $M^n$  in B, described by the function  $\tilde{e}_A(q)$  for q in a neighborhood of p. Then for any frame  $e_A(q)$  in B at x(q), we have  $e_{n+N} = \sum \xi_{\gamma} \tilde{e}_{\gamma}(q)$  and

(10) 
$$A_{n+Nij} = \sum_{\gamma} \xi_{\gamma} \widetilde{A}_{\gamma i j}, \quad \sum_{\gamma} \xi_{\gamma}^{2} = 1,$$

where  $\widetilde{A}_{\gamma ij}$  is the function  $A_{\gamma ij}$  restricted to the local cross-section.

By (6), we find that  $K_2(p, e_{\gamma})$  is given by

(11) 
$$\binom{n}{2} K_z(p, e_{\gamma}) = \sum_{i < j} (A_{\gamma i} A_{\gamma j j} - A_{\gamma i j}^z).$$

Combining (10) and (11), we find that

The right hand side is a quadratic form of  $\xi_{n+1}, \dots, \xi_{n+N}$ . Hence, choosing a suitable cross-section, we can write  $K_2(p, e_{n+N})$  as

(13) 
$$K_{2}(p, e_{n+N}) = \sum_{\gamma} \lambda_{\gamma-n}(p) \xi_{\gamma} \xi_{\gamma}, \quad \lambda_{1} \geq \lambda_{2} \geq \cdots \geq \lambda_{N}.$$

We may call this local cross-section of  $B \rightarrow F(M'')$  a Frenet cross-section

and such frame  $(p, e_1, \dots, e_n, \overline{e}_{n+1}, \dots, \overline{e}_{n+N})$  a Frenet frame. We call  $\lambda_a$ ;  $\alpha = 1, \dots, N$ , the  $\alpha$ -th scalar curvature of  $M^n$  in  $E^{n+N}$ . By means of the method of definition,  $\lambda_a$  is defined continuously on the whole manifold  $M^n$  and is differentiable on the open subset in which  $\lambda_1 > \lambda_2 > \dots > \lambda_N$ . Now, let  $\overline{e}_i = e_i$ , and  $\overline{e}_{\gamma} = \overline{e}_{\gamma}$ , where  $(p, e_1, \dots, e_n, \overline{e}_{n+1}, \dots, \overline{e}_{n+N})$  is the Frenet frame, then by (12) and (13), we have

(14) 
$$\binom{n}{2} \lambda_{\gamma-n}(p) = \sum_{i \leq j} (\widetilde{A}_{\gamma i}, \widetilde{A}_{\gamma j}, -\widetilde{A}_{\gamma i}^2).$$

Hence, we get

(15) 
$$\binom{n}{2} \sum_{\gamma} \lambda_{\gamma-n}(p) = \sum_{i \leq j} (\sum_{\gamma} \widetilde{A}_{\gamma ii} \widetilde{A}_{\gamma ij} - \widetilde{A}_{\gamma ij}^2) = \sum_{i \leq j} R_{ijji}.$$

Thus, if we define the scalar curvature S(p) as

(16) 
$$\binom{n}{2} S(p) = \sum_{i < j} R_{ijji}$$

Then S(p) is intrinsic and we have

**Proposition 1.1.** The scalar curvature S(p) and the  $\alpha$ -th scalar curvature satisfy the following relation:

(17) 
$$S(p) = \lambda_1(p) + \dots + \lambda_N(p).$$

### 2. Some results on α-th scalar curvature

Now, let us define an invariant by

(18) 
$$\rho(p) = \max\{\sqrt{|\lambda_1(p)|^n}, \dots, \sqrt{|\lambda_N(p)|^n}\}\$$
$$= \max\{\sqrt{|\lambda_1(p)|^n}, \sqrt{|\lambda_N(p)|^n}\}.$$

Then, from (7) and (13), we have

(19) 
$$K_{2}^{*}(p) = \int |K_{2}(p, e_{n+N})|^{\frac{n}{2}} d\sigma_{N-1} = \int |\sum \lambda_{\gamma-n}(p) \xi_{\gamma} \xi_{\gamma}|^{\frac{n}{2}} d\sigma_{N-1}$$
$$\leq \rho(p) \int (\sum \xi_{\gamma} \xi_{\gamma})^{\frac{n}{2}} d\sigma_{N-1} = \rho(p) c_{N-1}.$$

Accordingly, from Theorem A and (19), we get

(20) 
$$c_{N-1} \int_{M^n} \rho(p) \ dV \ge 2c_{n+N-1}.$$

If the equality of (20) holds, then by (19) we get

$$\int_{M^n} K_2^* dV = 2c_{n+N-1}.$$

Hence, by Theorem A, we know that  $M^n$  is imbedded as a hypersphere if n>2 and as a convex hypersurface if n=2. Therefore, we can easily derive that

$$\lambda_1(p) \ge 0$$
,  $\lambda_2(p) = \cdots = \lambda_N(p) = 0$ , for all  $p \in M^n$ .

Thus, by the equalities of (19) and (20), we find that the geodesic codimension is equal to 1. Hence, we have proved the following theorem:

**Theorem 2.1.** For an n-dimensional closed manifold  $M^n$  immersed in  $E^{n+N}$ , we have

(21) 
$$\int_{\mathcal{N}^n} \rho(p) dV \ge \frac{2c_{n+N-1}}{c_{N-1}}.$$

The equality of (21) holds when and only when  $M^n$  is imbedded as a hypersphere if n>2, and as a convex hypersurface if n=2 in an (n+1)-dimensional linear subspace of  $E^{n+N}$ .

From Theorem 2. 1, we have the following corollaries:

Corollary 2.1. Let  $M^n$  be an n-dimensional riemannian closed manifold. Then  $M^n$  can not be isometrically immersed in a euclidean space  $E^{n+N}$  with  $\rho(p) \leq \frac{2c_{n+N-1}}{c_{N-1}v(M^n)}$  except  $\rho(p) = constant$ , N=1 and  $M^n$  is an n-sphere, where  $v(M^n)$  denotes the volume of  $M^n$ .

Corollary 2.2. Let  $M^n$  be an n-dimensional riemannian closed manifold. If  $M^n$  is not an n-sphere and the scalar curvature S(p) of  $M^n$  satisfies

(22) 
$$\int_{M^n} \sqrt{|S(p)|^n} dV \leq c_n,$$

then  $M^{*}$  can not be isometrically immersed in  $E^{n+1}$ .

Remark 2.1. Flat torus in E' is an example that Corollary 2.2 is not true in general if  $N \ge 2$ .

Remark 2.2. If  $M^n$  is isometrically immersed in  $E^{n+1}$  as a closed hypersurface, then for any  $p \in M^n$  such that p is a nondegenerate critical point of a height function in the direction e. Then the second fundamental form at (p, e) is definite. Thus the scalar curvature S(p) is positive. This shows that every n-dimensional closed riemannian manifold  $M^n$  isometrically immersed in  $E^{n+1}$  must have positive scalar curvature S(p) at some points.

Furthermore, we can use the  $\alpha$ -th scalar curvature to characterize the hypersphere as follows:

**Theorem 2.2.** Let  $M^n$   $(n \ge 3)$  be an n-dimensional closed manifold immersed in  $E^{n+N}$ . Then

(23) 
$$\int_{M^n} (\lambda_1)^{\frac{1}{2}n} dV = c_n \quad and \quad \lambda_2 = \cdots = \lambda_N = 0$$

if and only if  $M^n$  is imbedded as a hypersphere in an (n+1)-dimensional linear subspace of  $E^{n+N}$ .

Proof. Assume that (23) holds, then, by (13), we have

$$K_2(p, e_{n+N}) = \lambda_1 \xi_1^2 \geq 0.$$

Thus we get

$$K_{2}^{*}(p) = \int \sqrt{(\lambda_{1}\xi_{1}^{2})^{n}} d\sigma_{N-1} = (\lambda_{1})^{\frac{1}{2}n} \int |\xi_{1}|^{n} d\sigma_{N-1}$$
$$= \frac{2c_{N+N-1}}{c_{N}} (\lambda_{1})^{\frac{1}{2}n}.$$

By integrating both sides of the above formula, we get

$$\int_{M^n} K_2^*(p) dV = \frac{2c_{n+N-1}}{c_n} \int_{M^n} (\lambda_1)^{\frac{1}{2}n} dV = 2c_{n+N-1}.$$

Thus, we know that  $M^n$  is imbedded as a hypersphere in an (n+1)-dimensional linear subspace of  $E^{n+N}$ . The converse of this is trivial.

**Remark 2.3.** If n=2, then Theorem 2.2 was treated in [1].

## 3. Submanifolds with S(p) = 0

The main object of this section is to prove the following theorem:

**Theorem 3.1.** Let  $M^{2m}$  be a 2m-dimensional closed manifold immersed in  $E^{2m+2}$  with scalar curvature S(p)=0. Then we have

(24) 
$$\int_{M^{2m}} (\lambda_1)^m dV = \frac{c_n}{2c_{m+1}} \int_{M^{2m}} K_2^* dV.$$

*Proof.* By the assumption, we have

$$\lambda_1(p) + \lambda_2(p) = S(p) = 0.$$

Hence, we have

$$K_{2}^{*}(p) = \int_{0}^{2\pi} |K_{2}(p, e_{2m+2})|^{m} dg = (\lambda_{1})^{m} \int_{0}^{2\pi} |\cos^{2}\theta - \sin^{2}\theta|^{m} dg$$
$$= (\lambda_{1})^{m} \int_{0}^{2\pi} |\cos^{2}\theta|^{m} d\theta = \frac{2c_{m+1}}{c_{m}} (\lambda_{1})^{m}.$$

Therefore, by integrating both sides of the above formula, we get (24).

In the special case, m=1, Theorem 3.1 reduces to a theorem of  $\overline{\text{Otsuki-[7]}}$ :

Theorem 3.2. Let M<sup>2</sup> be a flat torus immersed in E<sup>4</sup>. Then

(25) 
$$\int_{V^2} \lambda_1(p) dV \ge 2\pi^2.$$

Equality holds if and only if  $\int_{u^2} K_2^* dV = 8\pi^2$ .

Theorem 3. 2 follows immediately from Theorem 3. 1 and (9).

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