Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

Proof

The rough sketch of the proof The details of the proof On a global estimate for Fourier transforms of smooth rough paths

Keisuke HARA

(ACCESS Co., Ltd. \rightarrow ?)

26th Jan. 2012 @Nagoya Univ. (based on a joint work with T.Lyons)

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

An answer

Proof

The rough sketch of the proof The details of the proof

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

An answer

Proof

The rough sketch of the proof The details of the proof

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

An answe

Proof

The rough sketch of the proof The details of the proof

What is Smooth Rough Path?

- A "smooth rough path" is actually smooth.
- But it is actually a rough path in the sense of Rough Path Theory.
- It means the smooth path that satisfies the rough path estimates.

The control function $\omega(s, t)$

You know our famous control function $\omega(s,t)$ of rough path theory.

So, we skip the definition!

(But, remember the important property:

$$\omega(s, u) + \omega(u, t) \leq \omega(s, t)$$

for $s \leq u \leq t$.)

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

Proof

The rough sketch of the proof The details of the proof

Minimal definition of Smooth rough paths

Let $p \ge 1$ be a real number. Let $F : \mathbb{R} \to \mathbb{R}^d$ be an infinitely differentiable function and $F_{s,t}^i$ be the *i*th iterated integral:

$$F_{s,t}^i = \int \cdots \int_{s < u_1 < \cdots < u_i < t} dF_{u_1} \otimes \cdots \otimes dF_{u_i} \quad (i = 1, 2, 3, \dots),$$

and let $\|\cdot\| = \|\cdot\|_i$ be the norm in the *i*th tensor product space of \mathbb{R}^d .

If there exists a control function ω with a constant M such that

$$\|F_{s,t}^i\|^{p/i} \le \omega(s,t) < M < \infty \quad (i = 1, 2, \dots, \lfloor p \rfloor)$$

for any $-\infty < s < t < \infty$, we call F a (*p*-)smooth rough path with a global control ω .

(That is all. We need not assume the Chen's identity because it always holds by Chen's theorem for smooth paths.)

Keisuke HARA

Introduction

- What is Smooth Rough Path? Motivation and NLFT
- Problem and Answer
- Problem
- An answer

Proof

The rough sketch of the proof The details of the proof

What for?

- A toy model of the (serious) rough path theory.
 - Easy to define. (Need not functional analytic setting, etc.)
 - Easy to study. (You can freely use any analytic technique. After that, consider what the essential points are as rough paths.)
- Interesting as itself.
 - Study the global oscillation of a path.
 - Another possibility of the power of 'rough path theory'

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

An answer

Proof

The rough sketch of the proof The details of the proof

A secret motivation (related to Nonlinear Fourier transform)

- It seems that we need the deep estimate of Fourier transforms to study the Nonlinear Fourier transform.
- Especially the estimate of the global oscillation seems important.
- We might be able to define and study the NLFT with rough path theory!
- (But, it must be very hard task to get the deeper estimate for the Fourier transform enough to study NLFT....)

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

Proof

The rough sketch of the proof The details of the proof

What is Nonlinear Fourier transform? A rough sketch of NLFT according to T. Tao and C. Thiele. We like to define the Nonlinear Fourier transform of a function $f : \mathbb{R} \to \mathbb{C}$ under some reasonable conditions.

Let the matrix-valued Dirac operator L = L(f) be

$$L = \left(\begin{array}{cc} D & -f \\ f & -D \end{array}\right),$$

where D = d/dt is the differentiation operator. Consider the following eigenfunction problem.

$$L\left(egin{array}{c} \phi(k;t) \ \psi(k;t) \end{array}
ight) = ik \left(egin{array}{c} \phi(k;t) \ \psi(k;t) \end{array}
ight).$$

(Note that k is a real number because the operator L is anti-selfadjoint.)

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

An answe

Proof

The rough sketch of the proof The details of the proof We suppose that the eigenfunctions have some regularity and the boundary conditions $\phi(k; t) \sim e^{ikt}$, $\psi(k; t) \sim 0$ as $t \rightarrow +\infty$.

It is natural to set

$$\phi(k; t) = a(k; t)e^{ikt}$$
 and $\psi(k; t) = b(k; t)e^{-ikt}$,

considering the free case $f \equiv 0$. Then the equation becomes

$$\frac{d}{dt}a(k;t) = b(k;t)\overline{f(t)}e^{-2ikt},$$

$$\frac{d}{dt}b(k;t) = a(k;t)f(t)e^{2ikt}$$

with the boundary conditions $a(k; +\infty) = 1$ and $b(k; +\infty) = 0$. If the solutions exist, we define the nonlinear Fourier transform of f as

$$\widehat{f}[k] = \begin{pmatrix} a(k; -\infty) \\ b(k; -\infty) \end{pmatrix}.$$

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

An answe

Proof

The rough sketch of the proof The details of the proof

A smooth rough path and NLFT?

Let us rewrite those equations as follows:

$$P\left(\begin{array}{c}\overline{a(k;t)}\\b(k;t)\end{array}\right) = \overline{\left(\begin{array}{c}\underline{b(k;t)}\\a(k;t)\end{array}\right)} e^{ikt} dF(t), \quad (F'(t) = f(t)).$$

Or, the equivalent form in the real Euclidean space is

$$\begin{pmatrix} a_1 \\ -a_2 \\ b_1 \\ b_2 \end{pmatrix} = \begin{pmatrix} b_1 & b_2 \\ -b_2 & b_1 \\ a_1 & -a_2 \\ a_2 & a_1 \end{pmatrix} d \begin{pmatrix} \widetilde{F_1}(t) \\ \widetilde{F_2}(t) \end{pmatrix},$$

where

d

$$d\left(\begin{array}{c}\widetilde{F_{1}}(t)\\\widetilde{F_{2}}(t)\end{array}\right) = \left(\begin{array}{c}\cos kt & \sin kt\\-\sin kt & \cos kt\end{array}\right)d\left(\begin{array}{c}F_{1}(t)\\F_{2}(t)\end{array}\right)$$

and $F(t) = F_1(t) + iF_2(t)$ with real valued functions F_1 and F_2 .

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

- Problem and Answer
- Problem
- Proof
- The rough sketch of the proof The details of the proof

A secret (ambitious) plan

- This form shows a possibility that we might be able to study the NLFT through the input "rough signal" dF̃ = e^{ikt}dF with the rough path theory.
- For example, use the fundamental theorem like "the solution is also a rough path if the input signal is so"?
- establish the theory of smooth rough paths (or global rough path on non-compact interval), and check the rough path estimate of the input signals?

It is already non-trivial...

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem An answei

Proof

The rough sketch of the proof The details of the proof

Today's Problem (The first level estimate)

Let $1 and <math>F : \mathbf{R} \to \mathbf{R}$ be a smooth *p*-rough path, i.e., it has globally finite *p*-variation controlled by a control function ω_F .

Let us define the Fourier type integral $G^{\theta}(t)$ by $dG^{\theta}=e^{i\theta t}dF_t$, i.e.,

$$G^{ heta}(t) - G^{ heta}(s) = \int_s^t e^{i heta t} dF_t \quad ext{for } s < t.$$

Then, is it a smooth rough path? Or, does it has a globally finite p'-variation with a control $\omega_{G^{\theta},(p',\theta)}$ for some p'?

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

An answer

Proof

The rough sketch of the proof The details of the proof If we remember the point-wise convergence of Fourier transform, this problem is far from obvious. We will show the following answer as a partial result:

An answer

Suppose that $1 \le p < 2$ and F is a smooth p-rough path, or that it has the (globally) finite p-variation controlled by ω_F . If p < p' < 2, then $\omega_{G^{\theta},(p',\theta)}$ of G^{θ} is (globally finite) for almost every θ .

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

All dilsw

Proof

The rough sketch of the proof

I he details of t proof

The rough sketch of the proof

Our proof has the three components.

Estimate of the expectation of the integral with

- Lyons' basic lemma (Part 1)
- Young's idea in 2 dimension (Part 2)
- Apply Hambly-Lyons' dyadic argument to the estimate with a little trick (a time change according to a control ω(s, t)). (Part 3).

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

An answ

Proof

The rough sketch of the proof The details of the

Part 1 and 2

Get the following estimate of the second moment of the integral $\int_{S}^{T} e^{i\theta t} dF_t$ with Gaussian θ :

$$\mathbb{E}\left[\left|\int_{S}^{T} e^{i\theta t} dF_{t}\right|^{2}\right] = \int_{S}^{T} \int_{S}^{T} e^{-(t-s)^{2}/2} dF_{s} dF_{t}$$
$$\leq C \omega_{F}(S,T)^{2/p}.$$

This is not innocent as it looks. Actually we will carefully use Lyons' Lemma (Research Letters Paper, 1981) and Young's argument in two dimension.

▲□▼▲□▼▲□▼▲□▼ □ ● ●

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

Proof

The rough sketch of the proof The details of the proof

Part 3

We use the estimate above to apply Hambly-Lyons' dyadic argument (Hambly-Lyons, 1998).

Lemma (B.Hambly and T.J.Lyons (1998))

Suppose that $(X_{s,t}^k)$ is a continuous multiplicative functional on $\Delta(0,1)$. Then there exists a constant C(p) such that $(X_{s,t}^k)$ will have finite p-variation on [0,1] if

$$\sum_{n=0}^{\infty} n^{C(p)} \sum_{k=1}^{2^n} \max_{m \leq p} \left| X^m \left(\frac{k}{2^n} \right) - X^m \left(\frac{k+1}{2^n} \right) \right|^{p/m} < \infty.$$

Roughly saying, this argument is to paste the estimates on dyadic intervals like $[k/2^n, (k+1)/2^n](k = 0, ..., 2^n - 1)$ in a clever way to get an estimate on [0, 1].

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem An answer

Proof

The rough sketch of the proof The details of the proof We need to modify this argument a little because our integral is defined on the whole real line \mathbb{R} . For this, we will take a time change $\rho : [0,1] \to \mathbb{R}$ suitably (according to ω_F) and we already checked in Part 1 that our estimate for

$$\mathbb{E}\left[\left|\int_{\rho\left(\frac{k}{2^{n}}\right)}^{\rho\left(\frac{k+1}{2^{n}}\right)}e^{i\theta t}dF_{t}\right|^{2}\right]$$

is sharp enough for the dyadic argument to work.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

An answe

Proof

The rough sketch of the proof The details of the

Putting them together

$$\mathbb{E}\left[\left|\int_{\rho(k/2^{n})}^{\rho((k+1)/2^{n})} e^{i\theta t} dF_{t}\right|^{p'}\right]$$

$$\leq \mathbb{E}\left[\left|\int_{\rho(k/2^{n})}^{\rho((k+1)/2^{n})} e^{i\theta t} dF_{t}\right|^{2}\right]^{p'/2}$$

$$\leq (\operatorname{const}) \cdot \omega_{F}\left(\rho\left(\frac{k+1}{2^{n}}\right), \rho\left(\frac{k}{2^{n}}\right)\right)^{(2/\rho) \cdot (p'/2)}$$

$$\leq (\operatorname{const}) \cdot \omega_{F}\left(\rho\left(\frac{k+1}{2^{n}}\right), \rho\left(\frac{k}{2^{n}}\right)\right)^{p'/p}.$$

Now using the fact that we properly chose the time change ρ according to the control ω_F and that p < p' < 2, we will finally get the result thanks to Hambly-Lyons' dyadic argument. Actually,

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLF7

Problem and Answer Problem

An answe

Proof

The rough sketch of the proof

The details of the proof

we have

$$\mathbb{E}^{\theta} \left[\sum_{n=0}^{\infty} n^{C(p')} \sum_{k=1}^{2^n} \left| G^{\theta} \left(\rho\left(\frac{k}{2^n}\right) \right) - G^{\theta} \left(\rho\left(\frac{k+1}{2^n}\right) \right) \right|^{p'} \right] \\ \leq D(\rho) \omega_F(-\infty,\infty)^{p'/p} \sum_{n=0}^{\infty} n^{C(p')} 2^{n(1-(p'/p))} < \infty$$

by Beppo-Levi.

We have checked the assumption of Hambly-Lyons' lemma for the almost surely paths. Therefore, the time-changed path $G^{\theta}(\rho(\cdot))$ has uniformly finite p'-variation by Hambly-Lyons' dyadic argument. Since the variation does not depend on any time-change, we reach the conclusion.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

An answe

Proof

The rough sketch of the proof The details of the proof

The detail of the proof: Part 1

Choose the Gaussian for θ (mean 0, variance σ^2). By Fubini's theorem and simple computations, we have

$$\mathbb{E}^{\theta} \left[\left| \int_{S}^{T} e^{i\theta s} dF_{s} \right|^{2} \right] = \mathbb{E}^{\theta} \left[\int_{S}^{T} e^{i\theta s} dF_{s} \int_{S}^{T} e^{-i\theta t} dF_{t} \right]$$
$$= \int_{S}^{T} \int_{S}^{T} \mathbb{E}^{\theta} \left[e^{i\theta(s-t)} \right] dF_{s} dF_{t}$$
$$= \int_{S}^{T} \int_{S}^{T} e^{-(t-s)^{2}\sigma^{2}/2} dF_{s} dF_{t}.$$

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

An answe

Proof

The rough sketch o the proof The details of the proof Now we want to estimate the Gauss type integral $\int_{S}^{T} \int_{S}^{T} e^{-(t-s)^{2}} dF_{t} dF_{s}$. Though it might seem innocent, this procedure is not easy. (The diagonal $\{(t,s): t = s\}$ seems dangerous!)

Proposition

Suppose that F and G are p-rough paths controlled by ω_F and ω_G respectably, which are both globally finite, i.e., $\omega_F(-\infty,\infty), \omega_G(-\infty,\infty) < M < \infty$ for a constant M. Suppose further that $\omega_F(0,\infty) = \omega_G(-\infty,0) = 0$ (, which means that F is constant on the right half line and G is constant on the left half line). Then, we have

$$\int_{\mathbb{R}}\int_{\mathbb{R}}e^{-(t-s)^{2}\sigma^{2}/2}dF_{s}dG_{t}\leq C\cdot\omega_{F}(-\infty,\infty)^{1/p}\omega_{G}(-\infty,\infty)^{1/p}$$

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

for a constant C > 0.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

Proof

The rough sketch of the proof The details of the proof Since the integral above does not contain the diagonal $\{s = t\}$, the result is a direct consequence of the following lemma by T.J.Lyons (Research Letters Paper, 1981).

Lemma (T.J.Lyons)

Let 1/p + 1/q > 1. If f is of finite q-variation controlled by ω_f and g is of finite p-variation controlled by ω_g , then the integral $z_t = \int_0^t f(s) dg(s)$ has its p-variation controlled by

$$(\|f\|_{\infty} + C_{1/p+1/q} \omega_f(0,t)^{1/q})^p \omega_g(0,t).$$

Therefore, in particular if f has bounded 1-variation and we take q = 1, the variation is at most $(||f||_{\infty} + C_{1/p+1} \omega_f(0, t))^p \omega_g(0, t).$

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

An answer

Proof

The rough sketch of the proof The details of the

proof

Since F_s has bounded variation, it has a limit as $s \to -\infty$. Therefore, we can apply a suitable time change $s \mapsto -s$ to make it run backwards. Let us denote the backward function by \tilde{F}_s . Note that this time change does not change the shape of the path, so it is a *p*-rough path again. Then, we have

$$\int_{\mathbb{R}} \int_{\mathbb{R}} e^{-(t-s)^2 \sigma^2/2} dF_s dG_t$$

$$= \int_{t>0} \int_{s<0} e^{-(t-s)^2 \sigma^2/2} dF_s dG_t$$

$$= \int_{t>0} \int_{s>0} e^{-(t+s)^2 \sigma^2/2} d\tilde{F}_s dG_t$$

$$\leq C \cdot \omega_{\tilde{F}} (-\infty, \infty)^{1/p} \omega_G (-\infty, \infty)^{1/p},$$

$$= C \cdot \omega_F (-\infty, \infty)^{1/p} \omega_G (-\infty, \infty)^{1/p},$$

if we can show the inequality above in the middle.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

Proof

The rough sketch o the proof The details of the proof Therefore, our task is to estimate

$$\int_0^\infty \left(\int_0^\infty e^{-(t+s)^2\sigma^2/2} dX_s\right) dY_t$$

for a *p*-rough paths *X*, *Y* controlled by global bounded control functions ω_X, ω_Y respectively defined on $[0, \infty]$. According to Lyons' Lemma (1981), It is enough to control the uniform norm and 1-variation of

$$Z(t)=\int_0^\infty e^{-(t+s)^2\sigma^2/2}dX_s.$$

First we check the uniform bound. Certainly the integral above makes sense since the integrand $s \mapsto \exp(-(t+s)^2 \sigma^2/2)$ is bounded and has globally bounded 1-variation thanks to Lemma above.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

Proof

The rough sketch of the proof The details of the proof More precisely, we have the Young integral bound at t > 0and taking the supremum over t > 0, we get

$$\begin{split} |Z(t)| &= \left| \int_0^\infty e^{-(t+s)^2 \sigma^2/2} dX_s \right| \\ &\leq \omega_X(0,\infty)^{1/p} (e^{-t^2 \sigma^2/2} + C_{1/p+1} e^{-t^2 \sigma^2/2}) \\ &\leq \omega_X(0,\infty)^{1/p} (1 + C_{1/p+1}) e^{-t^2 \sigma^2/2} \\ &\leq \omega_X(0,\infty)^{1/p} (1 + C_{1/p+1}), \end{split}$$

because the supremum norm and the 1-variational norm of $s \mapsto e^{-(s+t)^2 \sigma^2/2}$ are less than or equal to $e^{-(t+0)^2 \sigma^2/2}$. So we have got the uniform bound of |Z(t)|.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

An answe

Proof

The rough sketch of the proof The details of the proof Next, to estimates the 1-variational norm for Z(t), we study the derivative of Z(t):

$$Z(t)'=\int_0^\infty -(t+s)\sigma^2 e^{-(t+s)^2\sigma^2/2}dX_s.$$

Let us denote the integrand by -z(t), i.e.,

$$z(t) = (t+s)\sigma^2 e^{-(t+s)^2\sigma^2/2}$$
 $(t > 0),$

to see the behaviour closely. Simple calculation shows

$$z'(t) = \sigma^2 e^{-(t+s)^2 \sigma^2/2} \left(1 - \sigma^2 (t+s)^2\right).$$

Therefore, we have two cases. If $0 \le s \le 1/\sigma$, the maximum of z(t) occurs exactly once when $(t + s)^2 \sigma^2 = 1$ and the maximal value is $z(1/\sigma - s) = 1/\sigma \cdot \sigma^2 e^{-1/2} = \sigma e^{-1/2}$. On the other hand, if $s > 1/\sigma$, the function z(t) is monotone and the maximal value is $z(0) = s\sigma^2 e^{-s^2\sigma^2/2}$.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

An answe

Proof

The rough sketch of the proof The details of the proof This observation with Lyons' Lemma allows us to estimate of the integral Z'(t) as follows.

$$\begin{split} \left| Z'(t) \right| &= \left| \int_0^\infty -(t+s) \sigma^2 e^{-(t+s)^2 \sigma^2/2} dX_s \right| \\ &\leq \left\{ \begin{array}{l} \omega_X(0,\infty)^{1/p} (1+C_{1/p+1}) \sigma e^{-1/2}, & \text{if } t \leq 1/\sigma, \\ \omega_X(0,\infty)^{1/p} (1+C_{1/p+1}) t \sigma^2 e^{-t^2 \sigma^2/2}, & \text{if } t > 1/\sigma. \end{array} \right. \end{split}$$

Since $|Z(v) - Z(u)| = \left| \int_{u}^{v} Z'(t) dt \right| \le \int_{u}^{v} |Z'(t)| dt$, we can get the bound of the 1-variation of Z(t) with the estimate above for |Z'(t)| as follows.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

An answe

Proof

The rough sketch of the proof The details of the proof

For any sequence
$$0 \le t_0 < t_1 < t_2 < \cdots < \infty$$
, we have

$$\sum_{j} |Z(t_{j+1}) - Z(t_j)|$$

$$\le \sum_{j < k} |Z(t_{j+1}) - Z(t_j)| + |Z(1/\sigma) - Z(t_k)|$$

$$+ |Z(t_{k+1}) - Z(1/\sigma)| + \sum_{j \ge k+1} |Z(t_{j+1}) - Z(t_j)|$$

$$\le \omega_X(0, \infty)^{1/p} (1 + C_{1/p+1}) \sigma e^{-1/2} \frac{1}{\sigma}$$

$$+ \omega_X(0, \infty)^{1/p} (1 + C_{1/p+1}) \sigma^2 \int_{1/\sigma}^{\infty} t e^{-t^2 \sigma^2/2} dt$$

$$= 2\omega_X(0, \infty)^{1/p} (1 + C_{1/p+1}) e^{-1/2}.$$

Therefore, the 1-variation of $Z(t) = \int_0^\infty \exp(-(t+s)^2\sigma^2/2) dX_s$ is at most

 $2\omega_X(0,\infty)^{1/p}(1+C_{1/p+1})e^{-1/2}.$

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

An answe

Proof

The rough sketch of the proof The details of the proof Therefore, we have the estimates for the supremum norm and 1-variation norm of Z(t). Finally applying Lemma to $\int_0^\infty Z(t)dY_t$ again, we get

$$\begin{aligned} \left| \int_{0}^{\infty} \int_{0}^{\infty} e^{-(t+s)^{2}\sigma^{2}/2} dX_{s} dY_{t} \right| &= \left| \int_{0}^{\infty} Z(t) dY_{t} \right| \\ &\leq \omega_{Y}^{1/p}(0,\infty) \left((1+C_{1/p+1}) \omega_{X}^{1/p}(0,\infty) \right. \\ &+ C_{1/p+1}(1+C_{1/p+1}) 2e^{-1/2} \omega_{X}^{1/p}(0,\infty) \right) \\ &\leq C \omega_{X}^{1/p}(0,\infty) \omega_{Y}^{1/p}(0,\infty) \end{aligned}$$

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

for some constant C. Therefore, we have finished the 1st part.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

An answe

Proof

The rough sketch of the proof The details of the proof

The detail of the proof: Part 2

To show the following uniform bound

$$\int_{\mathbb{R}}\int_{\mathbb{R}}e^{-(t-s)^2\sigma^2/2}dF_sdG_t\bigg|\leq C\omega_F(-\infty,\infty)^{1/p}\omega_G(-\infty,\infty)^{1/p},$$

we show the next lemma with Young's trick and the key estimate in Part 1.

Definition

.)

Let $D = \{s_0 = -\infty < s_1 < s_2 < \cdots < s_r = +\infty\}$ be a finite partition of \mathbb{R} and consider the domain $\Delta(S, T) = \{(s, t) : S \leq s < t \leq T\}$, and the domain $\Delta^D = \Delta(-\infty, \infty) \setminus \bigcup_{i=1,\dots,r} \Delta(s_{i-1}, s_i)$. We define the *D*-approximate integral

$$I^D = \int \int_{\Delta^D} e^{-(t-s)^2 \sigma^2/2} dF_s dG_t.$$

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

Proof

The rough sketch of the proof The details of the proof We have the following estimate for the approximate integral I^D with the partition D.

Lemma

Suppose that $1 \le p < 2$. Then, the following estimate holds.

$$|I^D| \leq C \omega_F(-\infty,\infty)^{1/p} \omega_G(-\infty,\infty)^{1/p}$$

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

for some constant C.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

An answei

Proof

The rough sketch of the proof The details of the proof Without loss of generality, we can rescale F and G such that $\omega_F(-\infty,\infty) = \omega_G(-\infty,\infty)$. Let $\omega = \omega_F + \omega_G$. (So ω controls the both of F and G.) If r = 1, i.e., D is $(-\infty,\infty)$, then Δ^D is empty, $|I^D| = 0$, and no problem. Otherwise, there is an i such that

$$\omega(s_{i-1}, s_{i+1}) \leq \begin{cases} 2\frac{\omega(-\infty, \infty)}{r-2} & \text{if } r > 2, \\ \omega(-\infty, \infty) & \text{if } r = 2. \end{cases}$$

Let $D' = D \setminus \{s_i\}$. Then

$$I^{D} - I^{D'} = \int \int_{\Delta^{D} \setminus \Delta^{D'}} e^{-(t-s)^{2}\sigma^{2}/2} dF_{s} dG_{t}$$

= $2 \int \int_{[s_{i-1},s_{i}] \times [s_{i},s_{i+1}]} e^{-(t-s)^{2}\sigma^{2}/2} dF_{s} dG_{t}.$



Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

An answei

Proof

The rough sketch of the proof The details of the

I he details of th proof



Figure: Young's trick in 2 dimension

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

An answer

Proof

The rough sketch of the proof The details of the proof Now we apply our key estimate to this integral on the off-diagonal box and deduce that

$$\begin{split} |I^{D} - I^{D'}| &\leq \left| \int 2 \int_{[s_{i-1}, s_i] \times [s_i, s_{i+1}]} e^{-(t-s)^2 \sigma^2/2} dF_s dG_t \right| \\ &\leq C \omega_F(s_{i-1}, s_i)^{1/p} \omega_G(s_i, s_{i+1})^{1/p} \\ &\leq C' \left(\frac{\omega(-\infty, \infty)}{r-2} \right)^{2/p}. \end{split}$$

Since p < 2, we can sum up these estimates to get

$$|I^{D}| \leq C' 2^{2/p} \left(1 + \sum_{r=2}^{\infty} \left(\frac{2}{r}\right)^{2/p}\right)$$
$$\omega_{F}(-\infty, \infty)^{1/p} \omega_{G}(-\infty, \infty)^{1/p}$$

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

uniformly in *D*. So, we have finished the second part.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

Proof

The rough sketch of the proof The details of the proof

The detail of the proof: Part 3

Let us recall the Hambly-Lyons' dyadic argument.

Lemma (B.Hambly and T.J.Lyons (1998))

Suppose that $(X_{s,t}^k)$ is a continuous multiplicative functional on $\Delta(0,1)$. Then there exists a constant C(p) such that $(X_{s,t}^k)$ will have finite p-variation on [0,1] if

$$\sum_{n=0}^{\infty} n^{C(p)} \sum_{k=1}^{2^n} \max_{l \leq p} \left| X^l \left(\frac{k}{2^n} \right) - X^l \left(\frac{k+1}{2^n} \right) \right|^{p/l} < \infty.$$

But our object G^{θ} is defined on \mathbb{R} instead of [0, 1]. Therefore we need a little work to adjust the situation.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer Problem

An answe

Proof

The rough sketch of the proof The details of the proof To adjust our functions to Hambly-Lyons' lemma, we prepare a suitable time change. Our time change should be not only a map from [0, 1] to \mathbb{R} , but also go well with the control function.

Lemma

If ω is a control function where $\omega(-\infty,\infty) < M < \infty$ for a constant M, then there exists a continuous strictly increasing function $\rho : [0,1] \rightarrow [-\infty,\infty]$ with the property that

 $\omega(\rho(u),\rho(v)) \leq M|u-v|.$

Proof. Consider $\tau(t) = \omega(-\infty, t)$. (Basically) the inverse of τ is $\rho : [0, 1] \rightarrow [-\infty, \infty]$. (You need to check it works well.)

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLFT

Problem and Answer

Problem

An answe

Proof

The rough sketch of the proof The details of the proof

The detail of the proof: Putting all together Now we can put all together to get the result.

$$\begin{split} \mathbb{E}^{\theta} \left(\left| \int_{\rho(k/2^{n})}^{\rho((k+1)/2^{n})} e^{i\theta t} dF_{u} \right|^{2} \right)^{p'/2} \\ &= \left| \int_{\rho(k/2^{n})}^{\rho((k+1)/2^{n})} \int_{\rho(k/2^{n})}^{\rho((k+1)/2^{n})} e^{-(t-s)^{2}\sigma^{2}/2} dF_{s} dF_{t} \right|^{p'/2} \\ &\leq D(p) \left(\omega_{F} \left(\frac{k}{2^{n}}, \frac{k+1}{2^{n}} \right) \right)^{(2/p)(p'/2)} \\ &\leq D(p) \left(\frac{\omega_{F}(-\infty, \infty)}{2^{n}} \right)^{(2/p)(p'/2)} \\ &= D(p) \omega_{F}(-\infty, \infty)^{p'/p} \cdot 2^{-n(p'/p)}, \end{split}$$

where we used the super-additivity of ω_F in the second inequality. Here it is very crucial to get the order $2^{-n(p'/p)}$ for p' > p.

Keisuke HARA

Introduction

What is Smooth Rough Path? Motivation and NLF7

Problem and Answer

An answe

Proof

The rough sketch of the proof The details of the proof This order assures us to satisfy the assumption of Hambly-Lyons' lemma in Section 3 as follows:

$$\begin{split} {}^{\theta} \left[\sum_{n=0}^{\infty} n^{C(p')} \sum_{k=1}^{2^n} \left| G^{\theta} \left(\rho\left(\frac{k}{2^n}\right) \right) - G^{\theta} \left(\rho\left(\frac{k+1}{2^n}\right) \right) \right|^{p'} \right] \\ & \leq D(p) \omega_F(-\infty,\infty)^{p'/p} \sum_{n=0}^{\infty} n^{C(p')} 2^{n(1-(p'/p))} < \infty \end{split}$$

by Beppo-Levi.

E

We have checked the assumption of Hambly-Lyons' lemma for the almost surely paths. Therefore, the time-changed path $G^{\theta}(\rho(\cdot))$ has uniformly finite p'-variation by Hambly-Lyons' dyadic argument. Since the variation does not depend on any time-change, we reach the conclusion.