

**ANALYTIC EXTENSION OF EXCEPTIONAL
CONSTANT MEAN CURVATURE ONE CATENOIDS
IN DE SITTER 3-SPACE**

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ABSTRACT. Catenoids in de Sitter 3-space S_1^3 belong to a certain class of space-like constant mean curvature one surfaces. In a previous work, the authors classified such catenoids, and found that two different classes of countably many exceptional elliptic catenoids are not realized as closed subsets in S_1^3 . Here we show that such exceptional catenoids have closed analytic extensions in S_1^3 with interesting properties.

1. INTRODUCTION.

We denote by S_1^3 the de Sitter 3-space, which is a simply-connected Lorentzian 3-manifold with constant sectional curvature 1. Let \mathbf{R}_1^4 be the Lorentz-Minkowski 4-space with the metric $\langle \cdot, \cdot \rangle$ of signature $(-+++)$. Then

$$S_1^3 = \{X \in \mathbf{R}_1^4; \langle X, X \rangle = 1\}$$

with metric induced from \mathbf{R}_1^4 . We identify \mathbf{R}_1^4 with the 2×2 Hermitian matrices $\text{Herm}(2)$ by

$$(t, x, y, z) \longleftrightarrow \begin{pmatrix} t+z & x+iy \\ x-iy & t-z \end{pmatrix},$$

where $i = \sqrt{-1}$. Then S_1^3 is represented as

$$S_1^3 = \{X \in \text{Herm}(2); \det X = -1\} = \{ae_3a^*; a \in \text{SL}(2, \mathbf{C})\},$$

where $a^* := {}^t\bar{a}$ is the conjugate transpose of a , and

$$e_3 := \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

To draw surfaces in S_1^3 , we use the *stereographic hollow ball model* given in [4] as follows:

$$(1) \quad \Pi : S_1^3 \ni (t, x, y, z) \longmapsto \frac{1}{\delta}(x, y, z) \in \mathbf{R}^3$$

$$\left(\delta := t + \sqrt{t^2 + x^2 + y^2 + z^2} = t + \sqrt{2t^2 + 1} \right).$$

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This projection Π is the composition of central projection of S_1^3 to the unit sphere S^3 centered at the origin in \mathbf{R}^4 and usual stereographic projection of S^3 into \mathbf{R}^3 from $(0, 0, 0, -1)$. The image of Π is the set

$$(2) \quad \mathcal{D}^3 := \left\{ \xi \in \mathbf{R}^3 ; \sqrt{2} - 1 < |\xi| < \sqrt{2} + 1 \right\},$$

where $|\xi| := \sqrt{\xi_1^2 + \xi_2^2 + \xi_3^2}$ for $\xi = (\xi_1, \xi_2, \xi_3)$.

In [1], the authors classified all *catenoids* in S_1^3 (i.e. weakly complete constant mean curvature one surfaces in S_1^3 of genus zero with two regular ends whose hyperbolic Gauss map is of degree one). There are three types of catenoids:

- elliptic catenoids,
- the parabolic catenoid, and
- hyperbolic catenoids.

Parabolic catenoids have only one congruence class, whose secondary Gauss map is given by

$$g = \frac{1 + \log z}{-1 + \log z},$$

and they are rotationally symmetric surfaces with one cone-like singular point and two embedded ends. On the other hand, the secondary Gauss maps of hyperbolic catenoids are of the form

$$g = \frac{g_0 - i}{g_0 + i}, \quad g_0 := \exp((m + i\tau) \log z) = z^{m+i\tau},$$

where m is a non-negative integer, and τ is a non-zero real number. When $m \neq 0$ (resp. $m = 0$), hyperbolic catenoids admit only cuspidal edge singularities (resp. cone-like singular points), see [1, Page 36]. Recently, in a joint work with Seong-Deog Yang, the authors [2] proved that all hyperbolic catenoids do not admit any analytic extension.

On the other hand, there are many subclasses of elliptic catenoids, whose secondary Gauss maps g are given by

- (i) $g = z^\alpha$ ($0 < \alpha < 1$),
- (ii) $g = z^\alpha$ ($\alpha > 1$),
- (iii) $g = z^m + c$ ($m = 2, 3, \dots$) with $c \in (0, \infty) \setminus \{1\}$,
- (iv) $g = z^m + 1$ ($m = 2, 3, \dots$),
- (v) $g = (z^m - 1)/(z^m + 1)$ ($m = 2, 3, \dots$).

Except for the two cases (iv) and (v), all elliptic catenoids are closed subsets of S_1^3 , since the singular sets of catenoids of type (i)–(iii) are compact. In this paper, we call the catenoids in the class (iv) (resp. (v)) *exceptional catenoids of type I* (resp. *exceptional catenoids of type II*) and we study these two classes.

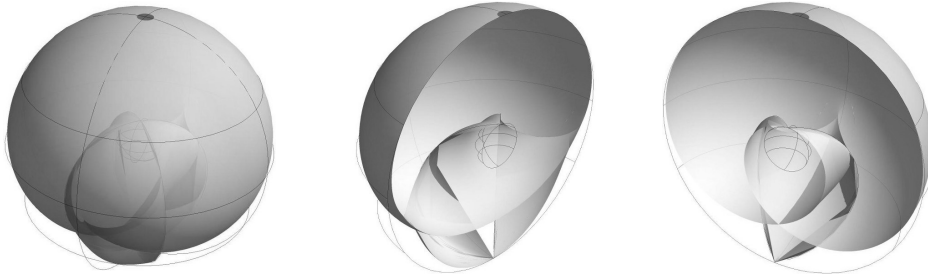


FIGURE 1. The image of f_2^I (left) and halves of it (center and right).

For each $m = 2, 3, \dots$, we set

$$(3) \quad F_m^I := \frac{z^{-\frac{m+1}{2}}}{2\sqrt{m}} \begin{pmatrix} (m+1)z & z((m-1)z^m - m - 1) \\ m-1 & (m+1)z^m - m + 1 \end{pmatrix}$$

and

$$(4) \quad F_m^{II} := \frac{z^{-\frac{m+1}{2}}}{2\sqrt{2m}} \begin{pmatrix} z((1-m)z^m + m + 1) & z((m-1)z^m + m + 1) \\ -(m+1)z^m + m - 1 & (m+1)z^m + m - 1 \end{pmatrix}.$$

The maps $f_m^J : \mathbb{C} \setminus \{0\} \rightarrow S_1^3$ defined by

$$f_m^J := F_m^J e_3 (F_m^J)^* \quad (J = I, II)$$

give the exceptional catenoids. These expressions are obtained by shifting m to $m - 1$ in [1, Prop. 4.9]. We will show that the image of each f_m^J ($J = I, II$) has an analytic extension \mathcal{C}_m^J which is a closed set in S_1^3 .

A subset \mathcal{A} of a manifold M^n is called *almost embedded* (resp. *almost immersed*) if there is a discrete subset D of \mathcal{A} such that $\mathcal{A} \setminus D$ is the image of an embedding (resp. an immersion) of a manifold into M^n . For example (cf. [1]),

- catenoids of class (iii) are not almost immersed,
- catenoids of class (i) are almost immersed, but not almost embedded,
- catenoids of class (ii) are almost embedded.

In Section 2, we investigate the geometric properties of f_m^I , and show that the image of each f_m^I has an analytic extension whose image is immersed outside of a compact set. See Figures 1, 2, 3, where f_2^I , \mathcal{C}_2^I and \mathcal{C}_3^I are drawn in the stereographic hollow ball model (1). In Section 3, we show that each \mathcal{C}_m^{II} can be realized as a warped product of a certain trochoid and hyperbola. In particular, \mathcal{C}_2^{II} and \mathcal{C}_3^{II} are almost embedded, and \mathcal{C}_m^{II} ($m \geq 4$) are almost immersed (cf. Section 3). See Figures 4, 5, where f_2^{II} , \mathcal{C}_2^{II} and \mathcal{C}_3^{II} are drawn in the stereographic hollow ball model (1) as well.

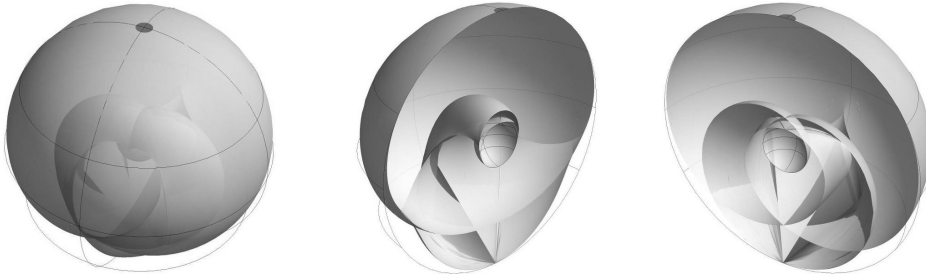


FIGURE 2. The set \mathcal{C}_2^I (left) and halves of it (center and right).

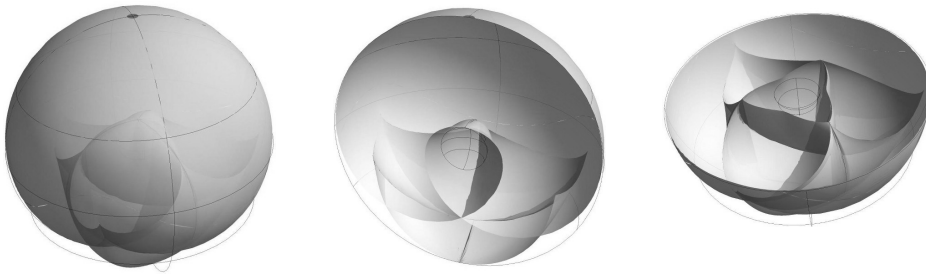


FIGURE 3. The set \mathcal{C}_3^I (left) and halves of it (center and right).

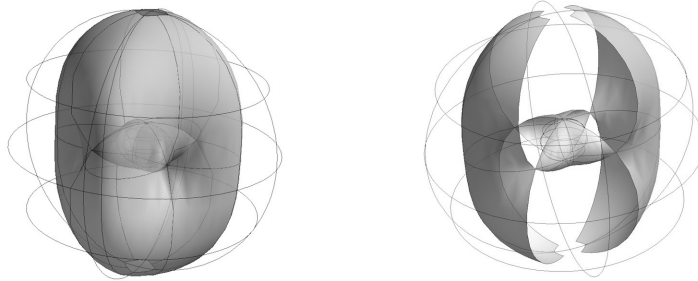


FIGURE 4. The set \mathcal{C}_2^{II} (left) and the image of f_2^{II} (right).

It is well-known that the de Sitter space S_1^3 can be compactified by including two spheres $\partial_{\pm}S_1^3$. These two sets $\partial_{\pm}S_1^3$ are called the *ideal boundaries*. In the stereographic hollow ball model, the relations

$$(5) \quad \partial_{\pm}S_1^3 = \{\xi \in \mathbf{R}^3; |\xi| = \sqrt{2} \mp 1\}$$

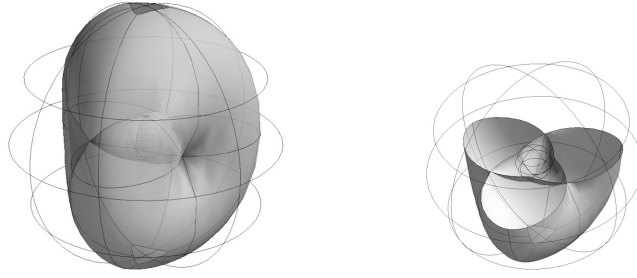


FIGURE 5. The set $\mathcal{C}_3^{\text{II}}$ and half of it.

hold (cf. (2)). If a subset \mathcal{A} of S_1^3 is closed, then each element of the set

$$\overline{\Pi(\mathcal{A})} \cap \partial \mathcal{D}^3 \subset \partial_- S_1^3 \cup \partial_+ S_1^3$$

is called an *endpoint*, where $\overline{\Pi(\mathcal{A})}$ is the closure of $\Pi(\mathcal{A})$ in \mathbf{R}^3 . Then the set $\overline{\Pi(\mathcal{C}_m^{\text{J}})} \cap \partial_+ S_1^3$ consists of one (resp. two) point(s) if $\text{J} = \text{I}$ and m is odd (resp. if $\text{J} = \text{I}$ and m is even, or $\text{J} = \text{II}$). On the other hand, $\overline{\Pi(\mathcal{C}_m^{\text{J}})} \cap \partial_- S_1^3$ always consists of two points, that is, the number of the endpoints of \mathcal{C}_m^{J} ($\text{J} = \text{I}, \text{II}$) is three or four (cf. Theorems 4 and 6). This is a remarkable phenomenon, since other elliptic catenoids in S_1^3 do not have any analytic extensions and have exactly two endpoints.

2. EXCEPTIONAL CATENOIDS OF TYPE I.

In this section, we show that f_m^{I} has an analytic extension. For each integer $m \geq 2$, we set

$$f_m^{\text{I}}(r, \theta) = (x_0(r, \theta), x_1(r, \theta), x_2(r, \theta), x_3(r, \theta)),$$

with $z = re^{i\theta}$ ($r > 0, \theta \in S^1 := \mathbf{R}/2\pi\mathbf{Z}$). Then

$$(6) \quad x_0 \pm x_3 = \frac{m^2 - 1}{4m} r^{\pm 1} \left(2 \cos m\theta - \frac{m \mp 1}{m \pm 1} r^m \right),$$

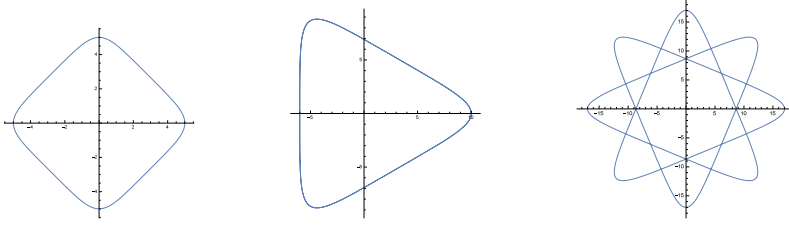
$$(7) \quad x_1 + ix_2 = \frac{(m - 1)^2}{4m} e^{i(m+1)\theta} + \frac{(m + 1)^2}{4m} e^{-i(m-1)\theta} - e^{i\theta} \frac{m^2 - 1}{4m} r^m.$$

We know that $f_m^{\text{I}}(r, \theta)$ has self-intersections, since it contains swallowtail singularities (cf. Proposition A.1 in Appendix A). The limit curve

$$(8) \quad \gamma_m(\theta) := \lim_{r \rightarrow 0} (x_1, x_2)$$

gives a closed regular planar curve.

A *hypo-trochoid* is a roulette traced by a point attached to a disk of radius r_c rolling along the inside of a fixed circle of radius r_m , where the point is

FIGURE 6. The trochoids for $m = 2, 3, 4$.

a distance d from the center of the interior circle. The parametrization of a hypo-trochoid is given by

$$\begin{aligned} x(s) &= (r_c - r_m) \cos s + d \cos \left(\frac{r_c - r_m}{r_m} s \right), \\ y(s) &= (r_c - r_m) \sin s - d \sin \left(\frac{r_c - r_m}{r_m} s \right). \end{aligned}$$

We prove the following:

Proposition 1. *The plane curve $\gamma_m(\theta)$ has the following properties:*

- (a) $\gamma_m(\theta + \pi) = (-1)^{m+1} \gamma_m(\theta)$ for $\theta \in \mathbf{R}$,
- (b) the image of γ_m is a convex curve if $m = 2, 3$,
- (c) γ_m is a hypo-trochoid with (cf. Figure 6)

$$r_c = \frac{m-1}{2}, \quad r_m = \frac{m^2-1}{4m}, \quad d = \frac{(m+1)^2}{4m}.$$

Proof. The first two assertions follow immediately. The last assertion follows from the expressions

$$\begin{aligned} x_1 &= \frac{(m-1)^2 \cos(m+1)\theta + (m+1)^2 \cos(m-1)\theta}{4m}, \\ x_2 &= \frac{(m-1)^2 \sin(m+1)\theta - (m+1)^2 \sin(m-1)\theta}{4m}. \end{aligned} \quad \square$$

We set $\Omega := \Omega^+ \cup \Omega^-$, where

$$\Omega^\pm := \{(r, \theta) \in \mathbf{R} \times S^1; \pm r > 0\} \quad (S^1 := \mathbf{R}/2\pi\mathbf{Z}).$$

The expressions (6) and (7) are meaningful for $r < 0$ as well, and f_m^1 can be extended to Ω . We denote this extension by $\tilde{f}_m^1: \Omega \rightarrow S_1^3$. If m is odd, then

$$(9) \quad \tilde{f}_m^1(-r, \theta + \pi) = \tilde{f}_m^1(r, \theta).$$

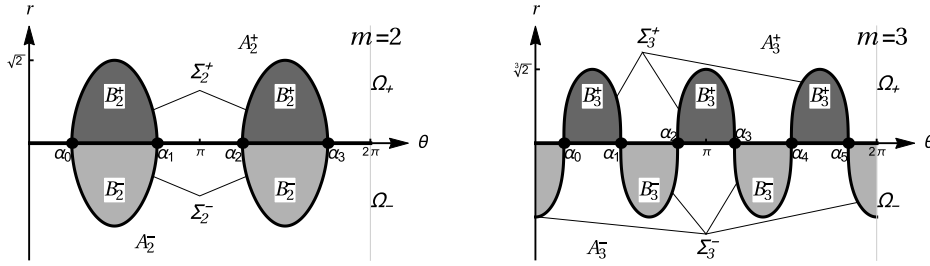


FIGURE 7. The domains of \tilde{f}_m^I and their singular sets.

In particular, if m is odd, the image of f_m^I coincides with that of \tilde{f}_m^I . On the other hand, if m is even,

$$\tilde{f}_m^I(-r, \theta) = \iota \circ \tilde{f}_m^I(r, \theta),$$

where ι is the isometric involution given by

$$(10) \quad \iota: S_1^3 \ni (t, x, y, z) \mapsto (-t, x, y, -z) \in S_1^3.$$

Thus, if m is even, $f_m^I(\Omega^+)$ and $f_m^I(\Omega^-)$ are congruent, but do not coincide with each other. The singular set of \tilde{f}_m^I is $\Sigma_m := \Sigma_m^+ \cup \Sigma_m^-$, where

$$\Sigma_m^\pm := \{(r, \theta) \in \Omega^\pm; r^m + 2 \cos m\theta = 0\},$$

each of which consists of m components. The image of each component of the singular set is a curve with singularities which is bounded in S_1^3 , whose endpoints are

$$(11) \quad P_k := (0, \gamma_m(\alpha_k), 0), \quad \alpha_k := \frac{2k+1}{2m}\pi \quad (k = 0, \dots, 2m-1).$$

We denote by A_m^\pm the domain in Ω^\pm containing a neighborhood of $r = \pm\infty$, and $B_m^\pm := \Omega^\pm \setminus \overline{A_m^\pm}$. Then we have the expressions

$$(12) \quad A_m^\pm = \{(r, \theta) \in \Omega^\pm; \epsilon^m(r^m + 2 \cos m\theta) > 0\},$$

$$(13) \quad B_m^\pm = \{(r, \theta) \in \Omega^\pm; \epsilon^m(r^m + 2 \cos m\theta) < 0\},$$

where ϵ is the sign of r (cf. Figure 7). We next consider the light-like lines

$$L_k := \{(t, \gamma_m(\alpha_k), -t); t \in \mathbf{R}\} \subset S_1^3$$

passing through P_k for $k = 0, 1, \dots, 2m-1$, and set

$$\mathcal{C}_m^I := \tilde{f}_m^I(\Omega) \cup L_0 \cup \dots \cup L_{2m-1}.$$

Then \mathcal{C}_m^I is the analytic extension of f_m^I . In fact,

Theorem 2. For each integer $m \geq 2$,

- (i) \mathcal{C}_m^I is a closed set of S_1^3 . In particular, if m is odd, then \mathcal{C}_m^I is the closure of the image of f_m^I . On the other hand, if m is even, then the closure of the image of f_m^I is just half of \mathcal{C}_m^I . The other half can be obtained by the isometric involution ι of S_1^3 given in (10).
- (ii) Moreover, \mathcal{C}_m^I is analytically immersed outside the compact set consisting of the image of Σ_m , and the points $\{(0, \gamma_m(\alpha_k), 0); k = 0, \dots, 2m - 1\}$.

Proof. By (6), $x_0(r, \theta)$ diverges for $r \rightarrow \pm\infty$. Take a sequence $\{\zeta_j = (r_j, \theta_j)\}_{j=1,2,\dots}$ on Ω such that $\lim_{j \rightarrow \infty} r_j = 0$. Taking a subsequence if necessary, we may assume $\{\zeta_j\}$ is included in Ω^+ or Ω^- , and $\lim_{j \rightarrow \infty} \theta_j = \beta$. If $\cos m\beta \neq 0$, (6) implies that $\lim_{j \rightarrow \infty} x_0(r_j, \theta_j)$ diverges. On the other hand, if $\cos m\beta = 0$, that is, $\beta = \alpha_k$ for some k , then $\lim_{j \rightarrow \infty} (x_0(\zeta_j) + x_3(\zeta_j))$ tends to 0, that is, $\tilde{f}_m^I(\zeta_j)$ is asymptotic to the line L_k . Conversely, for each point $Q_{k,t} := (t, \gamma_m(\alpha_k), -t) \in L_k$, we set

$$\zeta_j := \left(\frac{1}{j}, \frac{1}{m} \cos^{-1} \frac{4mt}{j(m^2 - 1)} \right) \quad (j = 1, 2, \dots),$$

where \cos^{-1} is the inverse function of \cos as a map

$$(14) \quad \cos^{-1}: (-1, 1) \rightarrow \left(m\alpha_k - \frac{\pi}{2}, m\alpha_k + \frac{\pi}{2} \right).$$

Then $\lim_{j \rightarrow \infty} \zeta_j = (0, \alpha_k)$ and $\lim_{j \rightarrow \infty} \tilde{f}_m^I(\zeta_j) = Q_{k,t}$, where α_k is as in (11).

Hence \mathcal{C}_m^I is the closure of the image of \tilde{f}_m^I , proving the first part of (i). The second part of (i) is already proven. We next prove (ii). Since \tilde{f}_m^I is an analytic immersion on $\Omega \setminus \Sigma_m$, it is sufficient to show that \mathcal{C}_m^I is parametrized analytically on a neighborhood of L_k , which gives an immersion on $L_k \setminus \{P_k\}$. For this purpose, we set $s := (\cos m\theta)/r$. Then the x_j ($j = 0, 1, 2, 3$) have the following expressions:

$$\begin{aligned} x_0 \pm x_3 &= \frac{m^2 - 1}{4m} r^{\pm 1} \left(2rs - \frac{m \mp 1}{m \pm 1} r^m \right), \\ x_1 + ix_2 &= \frac{e^{i \cos^{-1}(sr)/m}}{4m} \left((m - 1)^2 e^{i \cos^{-1}(sr)} \right. \\ &\quad \left. + (m + 1)^2 e^{-i \cos^{-1}(sr)} (m^2 - 1) r^m \right). \end{aligned}$$

Since $(\partial(x_1 + ix_2)/\partial r)|_{(0,s)} \neq 0$ if $s \neq 0$, one can easily check that $\tilde{f}_m^I(r, s)$ is an immersion at $(0, s)$ for each $s \in \mathbf{R} \setminus \{0\}$, which proves the assertion. \square

Remark 3. For the parametrization (r, s) as in the proof of Theorem 2, the origin $(r, s) = (0, 0)$ is a singular point for each $k = 0, 1, \dots, 2m - 1$, whose image is the point P_k given in (11). One can show that this parametrization gives a wave front on a neighborhood of $(0, 0)$, and the origin is a cuspidal edge (resp. swallowtail) when $m = 2$ (resp. $m = 3$), see Appendix A.

Next, we consider the endpoints of \mathcal{C}_m^1 . Let

$$(15) \quad \begin{aligned} p_{\pm} &:= (0, 0, \pm(\sqrt{2} - 1)) \in \partial_+ S_1^3, \\ n_{\pm} &:= (0, 0, \pm(\sqrt{2} + 1)) \in \partial_- S_1^3, \end{aligned}$$

where $\partial_{\pm} S_1^3$ are the ideal boundaries given in (5). We set

$$(16) \quad y := (y_1, y_2, y_3) := \Pi \circ f_m^I = \frac{1}{\delta}(x_1, x_2, x_3),$$

where $\delta = x_0 + \sqrt{2x_0^2 + 1}$ (cf. (1)).

Theorem 4. *If m is even (resp. odd), the set of endpoints of \mathcal{C}_m^1 is $\{p_{\pm}, n_{\pm}\}$ (resp. $\{p_-, n_{\pm}\}$). More precisely, let $\{\zeta_j = (r_j, \theta_j)\}$ be a sequence in Ω whose image under f_m^1 is unbounded. Then the following cases occur:*

- (1) $\lim_{j \rightarrow \infty} y(\zeta_j) = n_-$ holds when $\lim_{j \rightarrow \infty} r_j = +\infty$ (that is, $\{\zeta_j\}$ lies in Ω^+ and diverges).
- (2) When $\lim_{j \rightarrow \infty} r_j = -\infty$, that is, if $\{\zeta_j\}$ lies in Ω^- and diverges, then $\lim_{j \rightarrow \infty} y(\zeta_j)$ is p_+ (resp. n_-) if m is even (resp. odd).
- (3) When $r_j \rightarrow 0$ and $\{\zeta_j\}$ is contained in A_m^+ (resp. A_m^-, B_m^+, B_m^-), the limit of $y(\zeta_j)$ is obtained as in the following table:

The domain containing $\{\zeta_j\}$	A_m^+	A_m^-	B_m^+	B_m^-
$\lim_{j \rightarrow \infty} y(\zeta_j)$ for even m	p_-	n_+	n_+	p_-
$\lim_{j \rightarrow \infty} y(\zeta_j)$ for odd m	p_-	p_-	n_+	n_+

Proof. We rewrite (16) as

$$(17) \quad y_l = \frac{x_l/x_0}{1 + \operatorname{sgn}(x_0)\sqrt{2 + 1/(x_0)^2}} \quad (l = 1, 2, 3),$$

where $\operatorname{sgn}(x_0)$ denotes the sign of x_0 . By (6) and (7),

$$\begin{aligned} \lim_{r \rightarrow \pm\infty} \frac{x_3}{x_0} &= 1, & \lim_{r \rightarrow \pm\infty} \frac{x_l}{x_0} &= 0 \quad (l = 1, 2), \\ \lim_{r \rightarrow +\infty} x_0 &= -\infty, & \lim_{r \rightarrow -\infty} (-1)^m x_0 &= \infty, \end{aligned}$$

proving (1) and (2).

We prove (3) for the case that $\{\zeta_j\} \subset B_m^-$. Noticing that $r_j < 0$, (13) implies that

$$(-1)^m \left(r_j^{m-1} + \frac{\cos m\theta_j}{r_j} \right) > 0$$

holds for each j . Since $\{x_0(\zeta_j)\}$ is unbounded, so is $(\cos m\theta_j)/r_j$. Then the sign of $(\cos m\theta_j)/r_j$ is equal to $(-1)^m$ for sufficiently large j because r_j tends to 0. Then by (6), $\text{sgn}(x_0(\zeta_j)) = (-1)^m$. On the other hand, (6) implies that $\lim_{j \rightarrow \infty} x_3(\zeta_j)/x_0(\zeta_j) = -1$. Thus, we have

$$\lim_{j \rightarrow \infty} y_3(\zeta_j) = \frac{-1}{1 + (-1)^m \sqrt{2}} = 1 - (-1)^m \sqrt{2}.$$

Since x_1 and x_2 are bounded near $r = 0$, $y_l(\zeta_j)$ tends to 0 for $l = 1, 2$. Thus we have the conclusion. The other cases can be proved similarly. \square

3. EXCEPTIONAL CATENOIDS OF TYPE II.

Here we show that the image of the exceptional catenoid f_m^{II} in S_1^3 has an analytic extension. For each integer $m \geq 2$, we set

$$f_m^{\text{II}}(r, \theta) = (x_0(r, \theta), x_1(r, \theta), x_2(r, \theta), x_3(r, \theta)),$$

with $z = re^{i\theta}$ ($r > 0, \theta \in [0, 2\pi)$). By (4), f_m^{II} 's components are

$$(18) \quad \begin{aligned} x_0 &= \frac{1-m^2}{4m} \left(r + \frac{1}{r} \right) \cos m\theta, \\ x_3 &= \frac{1-m^2}{4m} \left(r - \frac{1}{r} \right) \cos m\theta, \\ x_1 &= -\frac{(m^2+1) \cos m\theta \cos \theta + 2m \sin m\theta \sin \theta}{2m}, \\ x_2 &= -\frac{(m^2+1) \cos m\theta \sin \theta - 2m \sin m\theta \cos \theta}{2m}, \end{aligned}$$

where $z = re^{i\theta}$ ($r > 0, \theta \in [0, 2\pi)$). The secondary Gauss map g_m of f_m^{II} is a meromorphic function on $\mathbf{C} \cup \{\infty\}$ given by (cf. [1, (39)])

$$g_m = (z^m - 1)/(z^m + 1).$$

Since the singular set Σ_m of the map f_m^{II} is

$$\Sigma_m = \{z \in \mathbf{C} \setminus \{0\} ; |g_m(z)| = 1\} = \{re^{i\theta} \in \mathbf{C} \setminus \{0\} ; \cos m\theta = 0\},$$

we have $\Sigma_m = \sigma_0 \cup \sigma_1 \cup \cdots \cup \sigma_{2m-1}$, where

$$(19) \quad \sigma_k := \left\{ z = re^{i\alpha_k} ; r > 0 \right\} \quad \left(\alpha_k := \frac{(2k+1)\pi}{2m} \right)$$

for $k = 0, \dots, 2m - 1$. In particular, if we set

$$(20) \quad \Omega_k := \left\{ r e^{i\theta}; \frac{(2k-1)\pi}{2m} < \theta < \frac{(2k+1)\pi}{2m}, r > 0 \right\},$$

then the union of the Ω_k ($k = 0, \dots, 2m - 1$) is the regular set of $f_m^{\mathbb{H}}$, that is, the regular set consists of a disjoint union of $2m$ sectors.

Proposition 5. *The map $f_m^{\mathbb{H}}$ satisfies:*

- (i) *For each $m \geq 2$, the image $f_m^{\mathbb{H}}(\sigma_k)$ consists of a point. More precisely,*

$$f_m^{\mathbb{H}}(\sigma_k) = (-1)^k (0, -\sin \alpha_k, \cos \alpha_k, 0),$$

where α_k is as in (19) ($k = 0, \dots, 2m - 1$).

- (ii) *The endpoints of the image of $f_m^{\mathbb{H}}$ are the four points p_{\pm} and n_{\pm} as in (15).*

Proof. Substituting $\theta = \alpha_k$ into (18) and using that $\cos m\theta = 0$ and $\sin m\theta = (-1)^k$ on σ_k , we get the first assertion.

To prove the second assertion, we remark that

$$(21) \quad \operatorname{sgn}(x_0) = (-1)^{k+1} \quad (\text{on } \Omega_k),$$

for each k , since $\operatorname{sgn}(\cos m\theta) = (-1)^k$. Take a sequence $\{z_j\}$ on $\mathbb{C} \setminus \{0\}$ such that $\Pi \circ f_m^{\mathbb{H}}(z_j)$ converges to one of the points in the ideal boundary. By (i), we may assume that each $z_j \notin \Sigma_m$. With finitely many sectors, we may also assume $\{z_j\} \subset \Omega_k$ for some k . Then $x_0(z_j)$ diverges to ∞ or $-\infty$ as $j \rightarrow \infty$, that is, $\{r_j + r_j^{-1}\}_{j=1,2,\dots}$ is unbounded, where $r_j := |z_j|$. Taking a subsequence, we may assume

$$(22) \quad \lim_{j \rightarrow \infty} r_j = 0 \quad \text{or} \quad \lim_{j \rightarrow \infty} r_j = \infty.$$

We set $y := \Pi \circ f_m^{\mathbb{H}}$. Since x_1 and x_2 are bounded (cf. (18)), $y_l(z_j) \rightarrow 0$ for $l = 1, 2$, where $y = (y_1, y_2, y_3)$. On the other hand, by (18) and (22), we have $\lim_{j \rightarrow \infty} (x_3(z_j)/x_0(z_j)) = \pm 1$. Thus, we have $\lim_{j \rightarrow \infty} y_3(z_j) = \pm\sqrt{2} \pm 1$, which proves (ii). □

It should be remarked that x_1, x_2 depend only on the variable θ , and

$$(x_1(\theta), x_2(\theta)) = -2\gamma_m(\theta)$$

holds. Here, γ_m is exactly the same hypo-trochoid as given in Proposition 1. For fixed θ , the image of the curve defined by $r \mapsto (x_0(r, \theta), x_3(r, \theta))$ coincides with

$$(23) \quad \left\{ (t, z) \in \mathbf{R}_1^2; t^2 - z^2 = \frac{(m^2 - 1)^2}{(2m)^2} \cos^2 m\theta, \operatorname{sgn}(\cos m\theta)t < 0 \right\}.$$

In particular, it is half of a hyperbola when $\cos m\theta \neq 0$. If $\cos m\theta = 0$, the image reduces to a point. So we can conclude that the real analytic extension of the image of $f_m^{\mathbb{I}}$ coincides with the set

$$\mathcal{C}_m^{\mathbb{I}} := \left\{ (t, x, y, z) \in \mathbf{R}_1^4; (x, y) = -2\gamma_m(\theta), \right. \\ \left. t^2 - z^2 = \frac{(m^2 - 1)^2}{(2m)^2} \cos^2 m\theta, \theta \in [0, 2\pi) \right\}.$$

For each $k = 0, \dots, 2m - 1$, the analytic extension $\mathcal{C}_m^{\mathbb{I}}$ contains a union of two light-like lines

$$L_k^{\pm} := \{(t, -\sin \alpha_k, \cos \alpha_k, \pm t); t \in \mathbf{R}\},$$

where α_k is as in (19). Moreover, $\mathcal{C}_m^{\mathbb{I}}$ is symmetric with respect to the isometric involution

$$S_1^3 \ni (t, x, y, z) \mapsto (t, \cos(2\alpha_k)x + \sin(2\alpha_k)y, \sin(2\alpha_k)x - \cos(2\alpha_k)y, z) \in S_1^3.$$

This involution fixes the two lines L_k^+ and L_k^- . Suppose that m is an odd integer. By (a) of Proposition 1, γ_m is π -periodic. In this case, one half of the hyperbola at $\theta + \pi$ is just the other half of the hyperbola (23) at θ , and $\mathcal{C}_m^{\mathbb{I}}$ coincides with the closure of the image of $f_m^{\mathbb{I}}$.

In the case m is even, $\mathcal{C}_m^{\mathbb{I}}$ does not coincide with the closure of the image of $f_m^{\mathbb{I}}$. Moreover, $\mathcal{C}_m^{\mathbb{I}}$ contains the image of the map $\iota \circ f_m^{\mathbb{I}}$, which is congruent to $f_m^{\mathbb{I}}$, where ι is the involution as in (10), and $\mathcal{C}_m^{\mathbb{I}}$ is just the closure of the union of the images of $f_m^{\mathbb{I}}$ and $\tilde{f}_m^{\mathbb{I}}$. Figure 4 shows $\mathcal{C}_m^{\mathbb{I}}$ and the image of $f_m^{\mathbb{I}}$ for $m = 2$.

Summarizing the above, we get the following:

Theorem 6. *For each $m = 2, 3, \dots$, the set $\mathcal{C}_m^{\mathbb{I}}$ gives the real analytic extension of the exceptional catenoid $f_m^{\mathbb{I}}$, and has the following properties:*

- (i) *The projection of $\mathcal{C}_m^{\mathbb{I}}$ into the xy -plane in \mathbf{R}_1^4 is the hypo-trochoid $-2\gamma_m$. Furthermore, the section of $\mathcal{C}_m^{\mathbb{I}}$ by a plane containing a point of the hypo-trochoid and perpendicular to the xy -plane is a hyperbola unless the plane passes through the cone-like singularity of $\mathcal{C}_m^{\mathbb{I}}$.*
- (ii) *$\mathcal{C}_m^{\mathbb{I}}$ is almost immersed and has four endpoints. Two of them lie in $\partial_+ S_1^3$ and the others lie in $\partial_- S_1^3$. Moreover, $\mathcal{C}_m^{\mathbb{I}}$ is almost embedded if $m = 2, 3$.*
- (iii) *If m is odd, then $\mathcal{C}_m^{\mathbb{I}}$ is the closure of the image of $f_m^{\mathbb{I}}$. On the other hand, if m is even, then the closure of the image of $f_m^{\mathbb{I}}$ is just half of $\mathcal{C}_m^{\mathbb{I}}$. The other half can be obtained by the isometric involution of S_1^3 given in (10).*

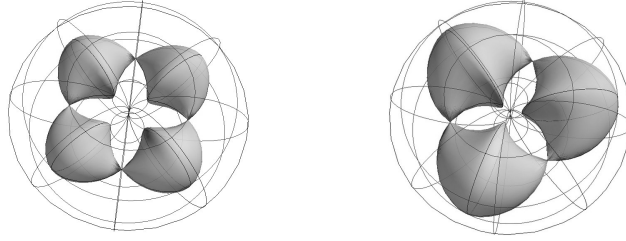


FIGURE 8. The images of \check{f}_m for $m = 2$ (left) and $m = 3$ (right).

When $m \geq 4$, $\mathcal{C}_m^{\text{II}}$ has self-intersections. It should be remarked that similar phenomena occur for parabolic or hyperbolic catenoids in the class of space-like maximal surfaces in \mathbf{R}_1^3 (see [3]).

Remark 7. As shown in [2], $\mathcal{C}_m^{\text{II}}$ is analytically complete, that is, $\mathcal{C}_m^{\text{II}}$ admits no analytic extension.

To end this paper, we remark that the replacement

$$s \mapsto is \quad (r = e^s)$$

of the parameter of f_m^{II} induces constant mean curvature surfaces in anti-de Sitter space. This induces a family of surfaces

$$\check{f}_m := (x_0(s, \theta), x_1(\theta), x_2(\theta), x_3(s, \theta))$$

given by $(x_0, x_3) = \frac{1-m^2}{2m} \cos m\theta (\cos s, \sin s)$, and x_1, x_2 as in (18), where $m = 2, 3, 4, \dots$. For each m , the corresponding surface lies in the space form

$$H_1^3(-1) := \{(t, x, y, z); t^2 - x^2 - y^2 + z^2 = -1\}$$

of constant curvature -1 realized in $(\mathbf{R}_2^4, + - - +)$. The image of \check{f}_m gives a compact almost immersed time-like surface of constant mean curvature one having a finite number of cone-like singularities. Moreover, if m equals 2 or 3, the surface is almost embedded in the sense given in the introduction. To draw the surfaces, we use the ‘solid torus model’ of $H_1^3(-1)$, that is, we define the following projection

$$\check{\Pi} : H_1^3(-1) \ni (t, x, y, z) \mapsto \frac{1}{\rho} \left(\left(1 + \frac{t}{\rho}\right) x, \left(1 + \frac{t}{\rho}\right) y, z \right) \in \mathbf{R}^3,$$

where $\rho := \sqrt{x^2 + y^2}$. The image of $\check{\Pi}$ is the interior of the solid torus obtained by rotating the unit disk with center $(1, 0, 0)$ about the third axis in \mathbf{R}^3 . The images of $\check{\Pi} \circ \check{f}_m$ for $m = 2, 3$ are given in Figure 8.

APPENDIX A. SINGULARITIES OF EXCEPTIONAL CATENOIDS OF TYPE I

In this appendix, we discuss properties of singularities of the exceptional catenoids of type I. By the criteria in [5, Theorem 3.4], we have the following:

Proposition A.1. *The singular set of f_m^I is*

$$\Sigma_m := \{z = re^{i\theta} \in \mathbf{C} \setminus \{0\}; r^m + 2 \cos m\theta = 0\}.$$

The m points

$$z = re^{i\theta}, \quad (r, \theta) = \left(2^{1/m}, \frac{1}{m}(2j+1)\pi\right), \quad (j = 0, \dots, m-1)$$

are swallowtails, and the $2m$ points

$$z = re^{i\theta}, \quad (r, \theta) = \begin{cases} (2^{1/(2m)}, \frac{1}{m}(\frac{3}{4} + 2j)\pi) \\ (2^{1/(2m)}, \frac{1}{m}(\frac{5}{4} + 2j)\pi), \end{cases} \quad (j = 0, \dots, m-1)$$

are cuspidal cross caps. Other points in Σ_m are cuspidal edges.

Next, we discuss singularities of the parametrization of \mathcal{C}_m^I near the line L_k ($k = 0, \dots, 2m-1$), as in the proof of Theorem 2. Without loss of generality, we may assume $k = 0$. Then the parametrization is expressed as

$$\hat{f}_m^I(r, s) := (x_0(r, s), x_1(r, s), x_2(r, s), x_3(r, s)),$$

where

$$(A.24) \quad \begin{aligned} x_0 + x_3 &:= \frac{m^2 - 1}{4m} \left(2r^2s - \frac{m-1}{m+1}r^{m+1}\right), \\ x_0 - x_3 &:= \frac{m^2 - 1}{4m} \left(2s - \frac{m+1}{m-1}r^{m-1}\right), \\ x_1 + ix_2 &:= \frac{(m-1)^2}{4m} e^{i(m+1)\theta} + \frac{(m+1)^2}{4m} e^{-i(m-1)\theta} - \frac{m^2 - 1}{4m} r^m e^{i\theta} \end{aligned}$$

and

$$(A.25) \quad \theta := \theta(r, s) = \frac{1}{m} \cos^{-1}(rs),$$

where we consider $\cos^{-1}(rs) \in [0, \pi]$. As shown in Theorem 2, the map \hat{f}_m^I is an immersion at $(0, s)$ if $s \neq 0$. We show the following:

Proposition A.2. *The map \hat{f}_m^I is a wave front near the origin, and the origin $(0, 0)$ is a cuspidal edge (resp. swallowtail) when $m = 2$ (resp. $m = 3$).*

Proof. Since

$$x_1(0, 0) + ix_2(0, 0) = -ie^{i\pi/(2m)} = \sin \frac{\pi}{2m} - i \cos \frac{\pi}{2m},$$

$x_1(0, 0) \neq 0$. Then

$$\pi: S_1^3 \ni (x_0, x_1, x_2, x_3) \mapsto (x_0 + x_3, x_0 - x_3, x_1) \in \mathbf{R}^3$$

gives a local coordinate system of S_1^3 around $\hat{f}_m^1(0, 0)$. So it is sufficient show the conclusion for the map

$$(A.26) \quad F(r, s) := \pi \circ \hat{f}_m^1(r, s) = (X(r, s), Y(r, s), Z(r, s)),$$

where

$$\begin{aligned} X(r, s) &:= 2(m+1)r^2s - (m-1)r^{m+1}, \\ Y(r, s) &:= 2(m-1)s - (m+1)r^{m-1}, \\ Z(r, s) &:= \frac{m-1}{m+1} \cos(m+1)\theta + \frac{m+1}{m-1} \cos(m-1)\theta - r^m \cos \theta. \end{aligned}$$

By (A.25),

$$\theta_r = -\delta s, \quad \theta_s = -\delta r \quad \left(\delta(r, s) := \frac{1}{m \sin m\theta(r, s)} \right)$$

hold. Then we have

$$\begin{aligned} F_r &= ((m+1)r(4s - (m-1)r^{m-1}), -(m^2-1)r^{m-2}, \\ &\quad (2s - mr^{m-1}) \cos \theta - sr\delta \lambda \sin \theta), \\ F_s &= (2(m+1)r^2, 2(m-1), 2r \cos \theta - r^2\delta \lambda \sin \theta), \end{aligned}$$

where

$$(A.27) \quad \lambda := 2s + r^{m-1}.$$

By a direct computation, we have $F_r \times F_s = \lambda \nu$, where

$$(A.28) \quad \begin{aligned} \nu &:= (\nu_1, \nu_2, \nu_3) \\ \nu_1 &:= -(m-1)(2 \cos \theta - r\delta(2s + (m+1)r^{m-1}) \sin \theta), \\ \nu_2 &:= -(m+1)r^2(2 \cos \theta - r\delta(2s - (m-1)r^{m-1}) \sin \theta), \\ \nu_3 &:= 4(m^2-1)r. \end{aligned}$$

Since

$$\nu(0, 0) = (-2(m-1) \cos(\pi/(2m)), 0, 0) \neq 0,$$

ν is the normal vector field of F , and λ in (A.27) is an identifier of singularities, that is, $\{(r, s); \lambda(r, s) = 0\}$ is the singular set. Since $d\lambda \neq 0$, the singular points of F are non-degenerate. Thus, the singular direction is

$$(A.29) \quad \xi := -2 \frac{\partial}{\partial r} + (m-1)r^{m-2} \frac{\partial}{\partial s}.$$

On other hand, since $2F_r + (m+1)r^{m-2}F_s = \mathbf{0}$ when $\lambda(r, s) = 0$,

$$(A.30) \quad \eta := 2\frac{\partial}{\partial r} + (m+1)r^{m-2}\frac{\partial}{\partial s}$$

is the null direction. Moreover,

$$d\nu(\eta)(0, 0) = (0, 0, 4(m^2 - 1)),$$

which is not proportional to $\nu(0, 0)$. Thus, the map F gives a wave front near the origin.

When $m = 2$, the singular direction and the null direction are linearly independent at the origin. Hence, by the criterion in [6, Proposition 1.3], the origin is a cuspidal edge.

Finally, when $m = 3$, the singular direction and the null direction are

$$\xi = -2\frac{\partial}{\partial r} + 2r\frac{\partial}{\partial s}, \quad \eta = 2\frac{\partial}{\partial r} + 4r\frac{\partial}{\partial s},$$

which are proportional at the origin. Moreover, $\det(\xi, \eta) = -12r$, where \det is the determinant function on the (r, s) -plane. Hence by the criterion in [6, Proposition 1.3], the origin is a swallowtail. \square

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